

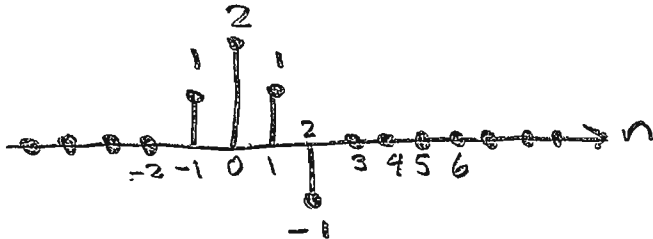
MODULE 3: TIME DOMAIN CONVOLUTION

- Recall from page 2.144 that any discrete-time signal $x[n]$ can be written as a sum of the shifts of $\delta[n]$:

$$x[n] = \dots + x[-2]\delta[n-2] + x[-1]\delta[n-1] + x[0]\delta[n-0] \\ + x[1]\delta[n-1] + x[2]\delta[n-2] + \dots \quad (*)$$

- For example,

$$x[n] = 1\delta[n+1] + 2\delta[n] + 1\delta[n-1] - 1\delta[n-2]$$



→ For this $x[n]$, we have:

$$x[-1] = 1$$

$$x[0] = 2$$

$$x[1] = 1$$

$$x[2] = -1$$

→ and $x[k] = 0$ for all the rest of the k 's.

- To save writing, we usually write eq. (*) above using a "capital Σ do loop":

$$x[n] = \sum_{k=-\infty}^{\infty} x[k]\delta[n-k] \quad (**)$$

⇒ This is equation (5.29) in the book.

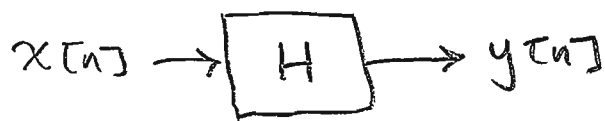
- In equations (*) and (**) on page 3.1, it is very important to remember that the $x[k]$ are numbers.

→ k is the loop counter

→ n is the independent (time) variable

⇒ For any given signal, like the $x[n]$ on page 3.1, the $x[k]$ are just numbers.

- Now suppose we have an LTI system H with impulse response $h[n]$:



- If the input is our signal $x[n]$ from page 3.1

$$x[n] = 1\delta[n+1] + 2\delta[n] + 1\delta[n-1] - 1\delta[n-2]$$

- Then the output signal $y[n]$ is given by:

$$y[n] = H\{x[n]\} = H\{1\delta[n+1] + 2\delta[n] + \delta[n-1] - \delta[n-2]\}.$$

→ Because the system is linear, the action of the system commutes with sums and we have:

$$y[n] = H\{1\delta[n+1]\} + H\{2\delta[n]\} + H\{1\delta[n-1]\} - H\{1\delta[n-2]\}$$



→ Also because the system is linear, the action of the system commutes with scalar multiplication and we have:

$$y[n] = 1H\{\delta[n+1]\} + 2H\{\delta[n]\} + 1H\{\delta[n-1]\} - 1H\{\delta[n-2]\}$$

→ Now, because the system is also time invariant, we know that for any $k \in \mathbb{Z}$, $H\{\delta[n-k]\} = h[n-k]$. I.e., the action of the system commutes with time shifts. Applying this, we have:

$$y[n] = 1h[n+1] + 2h[n] + 1h[n-1] - 1h[n-2].$$

⇒ In other words, when we write the input signal as a linear combination of the shifts of $\delta[n]$, it's easy to see that the output signal $y[n]$ is given by the same linear combination of the shifts of $h[n]$.

☆☆☆

- More generally, any input signal $x[n]$ can be written as a sum of the natural basis (the shifts of $\delta[n]$) according to:

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k], \quad (5.29)$$

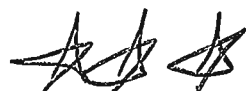
where the $x[k]$ are numbers.

- If we put $x[n]$ into the input of an LTI system H with impulse response $h[n]$



- Then the output signal $y[n]$ is given by

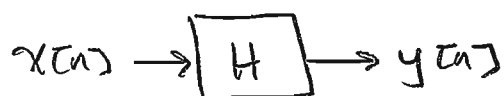
$$\begin{aligned} y[n] &= H\{x[n]\} \\ &= H\left\{\sum_{k=-\infty}^{\infty} x[k] \delta[n-k]\right\} \\ &= \sum_{k=-\infty}^{\infty} H\{x[k] \delta[n-k]\} \quad (\text{because } H \text{ is } \underline{\text{linear}}) \\ &= \sum_{k=-\infty}^{\infty} x[k] H\{\delta[n-k]\} \quad (\text{because } H \text{ is } \underline{\text{linear}}) \\ &= \sum_{k=-\infty}^{\infty} x[k] h[n-k] \quad (5.31) \quad (\text{because } H \text{ is } \underline{\text{time invariant}}) \end{aligned}$$



- The last equation on page 3.4 is called the discrete-time convolution of $x[n]$ and $h[n]$.
- This comes up so often that we have a special symbol for it: the asterisk " $*$ ".
- We write:

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k] \quad (5.31)$$

FACT: if the signal $x[n]$ is input to an LTI system H with impulse response $h[n]$,



then the output signal $y[n]$ is given by

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

"Convolution"

Note: we say:

- "The output of an LTI system is given by the convolution of the input signal with the impulse response."
- "To find the output, we convolve the input signal with the impulse response."

(The verb is convolve ... not convolute)

- The output signal

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

is just like any other discrete-time signal... we model it with a function $y[n]$ that has domain \mathbb{Z} and range \mathbb{R} or \mathbb{C} .

- So the basic problem is:

- Given $x[n]$ and $h[n]$, find $y[n]$.

- This is called discrete-time convolution.

- To solve it, we have to say what the number $y[n]$ is for every $n \in \mathbb{Z}$.

- Usually, we do this by writing down a formula for the function $y[n]$.

- We will talk a lot more about that in a minute.

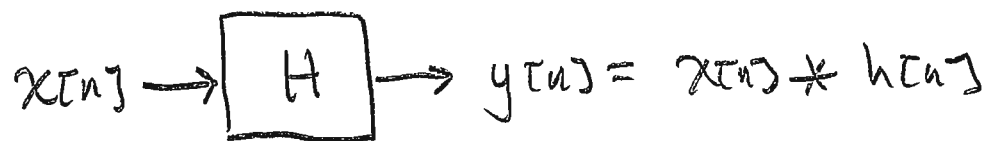
- But first, we are going to go over a couple of properties of the convolution operation itself...

- These properties can be useful for actually working out convolutions.

FACT: the convolution sum $\sum_{k=-\infty}^{\infty} x[k]h[n-k]$

can be thought of as an operation (or "operator") that gobbles up two signals ($x[n]$ and $h[n]$, for example) and combines them to make a third signal ($y[n]$ for example).

- Often, this comes up when we need to compute the output signal of an LTI system:



- But sometimes we also think of convolution as an operation that can combine two signals to make a third signal, even if there's not any system involved.

- So, sometimes we'll just say "let $x_1[n]$ and $x_2[n]$ be two signals and convolve them"...

- This means: find a third signal $x_3[n]$ such that

$$x_3[n] = x_1[n] * x_2[n] = \sum_{k=-\infty}^{\infty} x_1[k]x_2[n-k]$$

- To work the convolution, we must find the number $x_3[n]$ for every n .

- How do we compute this?

- Well, for each n ,

$$x_3[n] = \sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k]$$

- So, for each n , we have to execute the "do loop" $\sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k]$

- To execute the loop, we have to "work on" or "run" the loop counter... which is k

- And, in general, we have to do this for each value of n .

- For example, we have to find the number $x_3[7]$ for $n=7$. It is given by

$$x_3[7] = \sum_{k=-\infty}^{\infty} x_1[k] x_2[7-k]$$



- To understand how to do that, rewrite it as:

$$x_3[n] = \sum_{k=-\infty}^{\infty} x_1[k] x_2[-k - n]$$

\Rightarrow So, assuming that $x_1[n]$ and $x_2[n]$ are real-valued signals... so that conjugation doesn't do anything to them, we see that the number $x_3[n]$ is given by the dot product of $x_1[k]$ with $x_2[-k - n]$.

\Rightarrow The graph of $x_1[k]$ is obtained by taking the graph of $x_1[n]$ and simply changing the n 's to k 's.

\Rightarrow The graph of $x_2[-k - n]$ has a scale by -1 (a flip) and a shift by $n_0 = -n$.

- More generally, for each n ,

$$\begin{aligned} x_3[n] &= x_1[n] * x_2[n] = \sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k] \\ &= \sum_{k=-\infty}^{\infty} x_1[k] x_2[-k - n] \end{aligned}$$

... is a number that is given by the dot product of $x_1[k]$ with a "flipped and shifted" version of x_2 ... specifically $x_2[-k-n]$.

\uparrow \uparrow
 scale by -1 shift by " $-n$ "

\Rightarrow Always remember to do the shift first, then the scale... as we said back on page 2.100. ★
★
★

- But before we talk any more about the details of how to actually compute a convolution, let's go over the two convolution properties I mentioned back on the bottom of page 3.6...

① FACT: convolution is commutative:

$$x_1[n] * x_2[n] = x_2[n] * x_1[n] \quad (5.33)$$

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\Rightarrow In other words:

$$\sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k] = \sum_{k=-\infty}^{\infty} x_2[k] x_1[n-k]$$



- What this means to you from a practical standpoint:

⇒ If you are given two signals $x_1[n]$ and $x_2[n]$, and you are asked to compute the convolution

$$x_3[n] = x_1[n] * x_2[n],$$

⇒ Then you can put the "k" on x_1 and the "n-k" on x_2 to work it as

$$x_3[n] = \sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k]$$

→ In other words, you can "flip and shift" x_2 ...

⇒ OR you can do it the other way...

you can put the "n-k" on x_1 and put the "k" on x_2 to work it as

$$x_3[n] = \sum_{k=-\infty}^{\infty} x_2[k] x_1[n-k]$$

("flip and shift" x_1 instead)

★ Because convolution is commutative, you will get the exact same signal $x_3[n]$ either way.

→ The same number for every n.

Proof that convolution is commutative:

- Let $x_1[n]$ and $x_2[n]$ be two discrete-time signals.

- Let $x_3[n] = x_1[n] * x_2[n]$.

- Then: $x_3[n] = \sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k]$

Let $m = n - k$

Then $k = n - m$

→ when $k \rightarrow -\infty$, $m \rightarrow \infty$
when $k \rightarrow \infty$, $m \rightarrow -\infty$

$$\begin{aligned} \text{So } x_3[n] &= \sum_{k=-\infty}^{\infty} x_1[k] x_2[n-k] \\ &= \sum_{m=-\infty}^{\infty} x_1[n-m] x_2[m] \end{aligned}$$

(change variables
from k to m)

$$= \sum_{m=-\infty}^{\infty} x_1[n-m] x_2[m]$$

(order of adding
doesn't matter)

$$= \sum_{m=-\infty}^{\infty} x_2[m] x_1[n-m]$$

(order of multiplying
doesn't matter)

$$= \sum_{k=-\infty}^{\infty} x_2[k] x_1[n-k]$$

(write " k " for the
loop counter instead
of " m ")

$$= x_2[n] * x_1[n]$$



QED

2A FACT: convolution is associative:

$$(x_1[n] * x_2[n]) * x_3[n] = x_1[n] * (x_2[n] * x_3[n]) \quad (5.37)$$

- What it means to you:

→ If you have to convolve three signals together, it doesn't matter which two you do first.

→ The answer turns out the same whichever two you choose to do first.

- The proof of this is not hard, but it involves a lot of detailed steps that aren't important to us right now.

- So we're going to skip it. You will prove it in ECE 3793 (Signals & Systems).

(2B) FACT: convolution is distributive:

$$(x_1[n] + x_2[n]) * x_3[n] = (x_1[n] * x_3[n]) + (x_2[n] * x_3[n]) \quad (5.38)$$

- What it means to you:

→ you can add $x_1[n]$ and $x_2[n]$ first, then convolve with $x_3[n]$...

→ OR you can convolve each of $x_1[n]$ and $x_2[n]$ with $x_3[n]$ first... and then add those two...

⇒ The final result signal is exactly the same either way.

- As with associativity, the proof of this is not hard, but we're going to skip it because we don't want to get bogged down in the details.

- you will prove it in ECE 3793.

CONVOLUTION WITH DELTAS

- In a few minutes, we are going to learn a powerful general method for doing convolution that will always work.

- But it may seem a little bit complicated at first.

- There are certain cases where a simpler method will also work.

★ { - The simpler method will work when we have }
★ { to convolve two signals that can both be }
written as short sums of the shifts of $\delta[n]$. }

- For example, if

$$x[n] = \delta[n] + 2\delta[n-1] + 3\delta[n-2]$$

and

$$h[n] = \frac{1}{2}\delta[n] - \frac{1}{2}\delta[n-1]$$

\Rightarrow Both $x[n]$ and $h[n]$ are short sums of the shifts of $\delta[n]$

\Rightarrow The simpler method will work for finding the convolution

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k].$$

- To understand how the simpler method works, we need a few simple facts.

FACT 1 : For any discrete-time signal $x[n]$,
 $x[n] * \delta[n] = x[n]$. $///$

Proof : $x[n] * \delta[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$ (by definition)
 $= \sum_{k=-\infty}^{\infty} \delta[k] x[n-k]$ (because convolution is commutative)

$= \dots + \underbrace{\delta[-2] x[n+2]}_{\substack{\leftarrow \text{zero} \\ k=-2 \text{ term}}} + \underbrace{\delta[-1] x[n+1]}_{\substack{\leftarrow \text{zero} \\ k=-1 \text{ term}}} + \underbrace{\delta[0] x[n-0]}_{\substack{\leftarrow \text{one} \\ k=0 \text{ term}}} \\
+ \underbrace{\delta[1] x[n-1]}_{\substack{\leftarrow \text{zero} \\ k=1 \text{ term}}} + \underbrace{\delta[2] x[n-2]}_{\substack{\leftarrow \text{zero} \\ k=2 \text{ term}}} + \dots$

$=$ just the $k=0$ term (because $\delta[k] = \begin{cases} 1, & k=0 \\ 0, & \text{otherwise} \end{cases}$)

$= 1 x[n-0]$

$= x[n]$ $///$

☆☆☆

In words: convolution with $\delta[n]$ does not change the signal !!

FACT 2: For any discrete-time signal $x[n]$,

$$x[n] * \delta[n-5] = x[n-5]$$

★ In words: convolution with $\delta[n-5]$ shifts the signal to the right by 5.

Proof: $x[n] * \delta[n-5] = \sum_{k=-\infty}^{\infty} x[k] \delta[(n-5)-k]$

$$= \sum_{k=-\infty}^{\infty} \delta[k-5] x[n-k] \quad \left(\begin{array}{l} \text{because convolution} \\ \text{is commutative} \end{array} \right)$$

→ There is only one nonzero term in the sum

→ It is the $k=5$ term

→ On that term $k=5$ and $\delta[k-5] = \delta[0] = 1$

= just the "k=5" term

$$= 1 \cdot x[n-5]$$

$$= x[n-5] \quad //$$

FACT 3: More generally, for any discrete time signal $x[n]$ and any integer shift amount $n_0 \in \mathbb{Z}$,

$$x[n] * \delta[n-n_0] = x[n-n_0] \quad (5.36)$$

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~~AA~~ In words: convolution with a shifted delta shifts the signal by the same amount.

Proof:

$$\begin{aligned} x[n] * \delta[n-n_0] &= \sum_{k=-\infty}^{\infty} x[k] \delta[(n-n_0)-k] \\ &= \sum_{k=-\infty}^{\infty} \delta[k-n_0] x[n-k] \quad \left(\begin{array}{l} \text{because} \\ \text{convolution is} \\ \text{commutative} \end{array} \right) \\ &= \text{just the "k=n}_0\text{" term} \\ &= 1 x[n-n_0] \\ &= x[n-n_0]. \quad \text{//} \end{aligned}$$

\Rightarrow This works for any integer shift amount n_0 , including n_0 positive, n_0 negative, and $n_0=0$.

EXAMPLES : Good for any $x[n]$

$$x[n] * \delta[n-2] = x[n-2] \quad (n_0 = 2)$$

$$x[n] * \delta[n+3] = x[n+3] \quad (n_0 = -3)$$

$$x[n-1] * \delta[n-2] = x[n-3]$$

→ In this case, $x[n]$ was already shifted by 1. Convolution with $\delta[n-2]$ shifts him by two more.

$$x[n+3] * \delta[n-2] = x[n+1]$$

$$x[n-1] * \delta[n+4] = x[n+3]$$

Some more Specific Examples:

$$\delta[n] * \delta[n] = \delta[n]$$

$$\delta[n] * \delta[n-1] = \delta[n-1]$$

$$\delta[n-1] * \delta[n-1] = \delta[n-2]$$

$$\delta[n-2] * \delta[n] = \delta[n-2]$$

$$\delta[n-2] * \delta[n-1] = \delta[n-3]$$

$$\left\{ \left(\frac{1}{2}\right)^n u[n] \right\} * \delta[n-1] = \left(\frac{1}{2}\right)^{n-1} u[n-1]$$

$$\left\{ \left(\frac{1}{2}\right)^n u[n] \right\} * \delta[n+2] = \left(\frac{1}{2}\right)^{n+2} u[n+2]$$

FACT 4 : Convolution is linear.

- For any three discrete-time signals

$x_1[n]$, $x_2[n]$, and $x_3[n]$

- And any two constants $a, b \in \mathbb{C}$,

$$(ax_1[n] + bx_2[n]) * x_3[n]$$

$$= a(x_1[n] * x_3[n]) + b(x_2[n] * x_3[n]).$$

→ This is a slightly more advanced version of the distributive property (2B) that we had back on page 3.14.

Proof : $(ax_1[n] + bx_2[n]) * x_3[n]$

$$= \sum_{k=-\infty}^{\infty} (ax_1[k] + bx_2[k]) x_3[n-k]$$

$$= \sum_{k=-\infty}^{\infty} ax_1[k] x_3[n-k] + b \sum_{k=-\infty}^{\infty} x_2[k] x_3[n-k]$$

$$= a \sum_{k=-\infty}^{\infty} x_1[k] x_3[n-k] + b \sum_{k=-\infty}^{\infty} x_2[k] x_3[n-k]$$

$$= a(x_1[n] * x_3[n]) + b(x_2[n] * x_3[n])$$



NOTE: FACT 1 from page 3.16 ($x[n] * \delta[n] = x[n]$)
and FACT 2 from page 3.17 ($x[n] * \delta[n-5] = x[n-5]$)
are both really just special cases of FACT 3
from page 3.18: $x[n] * \delta[n-n_0] = x[n-n_0]$.

→ If we take $n_0=0$, then FACT 3
becomes $x[n] * \delta[n] = x[n]$

→ If we take $n_0=5$, then FACT 3 becomes
 $x[n] * \delta[n-5] = x[n-5]$.

⇒ So now let's use FACT 3 and FACT 4 to work
the example convolution problem we had all
the way back on page 3.15.

GIVEN: $x[n] = \delta[n] + 2\delta[n-1] + 3\delta[n-2]$
 $h[n] = \frac{1}{2}\delta[n] - \frac{1}{2}\delta[n-1]$

FIND: the signal $y[n] = x[n] * h[n]$



SOLUTION :

$$y[n] = x[n] * h[n]$$

$$= x[n] * \left(\frac{1}{2}\delta[n] - \frac{1}{2}\delta[n-1] \right)$$

$$= \frac{1}{2}(x[n] * \delta[n]) - \frac{1}{2}(x[n] * \delta[n-1])$$

$$= \frac{1}{2}x[n] - \frac{1}{2}x[n-1]$$

$$= \frac{1}{2} \underbrace{(\delta[n] + 2\delta[n-1] + 3\delta[n-2])}_{x[n]}$$

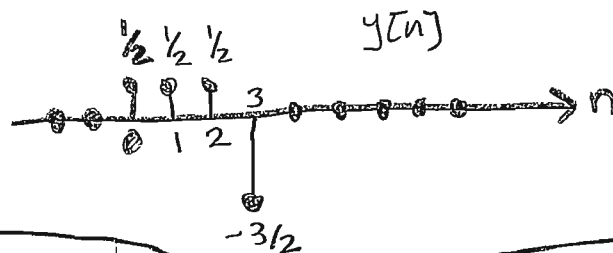
$$- \frac{1}{2} \underbrace{(\delta[n-1] + 2\delta[n-2] + 3\delta[n-3])}_{x[n-1]}$$

$$= \frac{1}{2}\delta[n] + \delta[n-1] + \frac{3}{2}\delta[n-2]$$

$$- \frac{1}{2}\delta[n-1] - \delta[n-2] - \frac{3}{2}\delta[n-3]$$

$$= \frac{1}{2}\delta[n] + \frac{1}{2}\delta[n-1] + \frac{1}{2}\delta[n-2] - \frac{3}{2}\delta[n-3]$$

$$y[n] = \frac{1}{2}\delta[n] + \frac{1}{2}\delta[n-1] + \frac{1}{2}\delta[n-2] - \frac{3}{2}\delta[n-3]$$



- Here's another example:

A discrete-time LTI system H has impulse response

$$h[n] = \delta[n] - 2\delta[n-1] + \delta[n-2].$$

The system input is given by

$$x[n] = \delta[n+1] + 3\delta[n] + \delta[n-1].$$



FIND the output signal $y[n]$.

SOLUTION

$$\begin{aligned} y[n] &= x[n] * h[n] \\ &= x[n] * (\delta[n] - 2\delta[n-1] + \delta[n-2]) \\ &= (x[n] * \delta[n]) - 2(x[n] * \delta[n-1]) + (x[n] * \delta[n-2]) \\ &= x[n] - 2x[n-1] + x[n-2] \\ &= \delta[n+1] + 3\delta[n] + \delta[n-1] \\ &\quad - 2\delta[n] - 6\delta[n-1] - 2\delta[n-2] \\ &\quad + \delta[n-1] + 3\delta[n-2] + \delta[n-3] \\ &= \delta[n+1] + \delta[n] - 4\delta[n-1] + \delta[n-2] + \delta[n-3] \end{aligned}$$

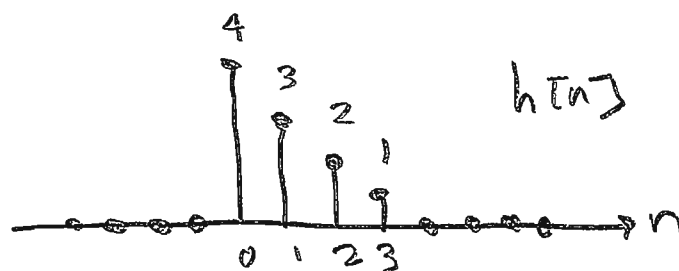
Reminder from page 3.15: this "simpler method" works when we have to convolve two signals that can both be written as short sums of the shifts of $\delta[n]$. ~~AAA~~

- But this simpler "convolution with deltas" method will not work at all if either of the two signals is infinite in length... for example, if $h[n] = (\frac{1}{2})^n u[n]$.
- It is also very inconvenient if either of the two signals is too long to be written as a short sum of the shifts of $\delta[n]$.
- For those types of cases, we need the more general method.

GENERAL METHOD FOR COMPUTING CONVOLUTIONS

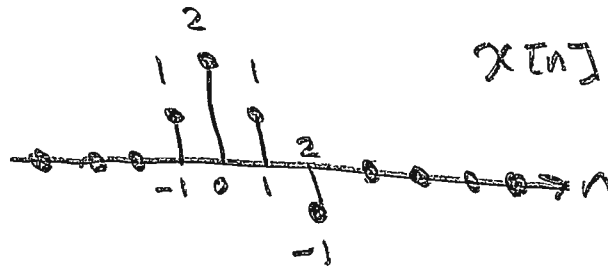
- Some people call this method "graphical convolution"
 - The reason is that we will typically need to draw graphs of $x[k]$ and $h[n-k]$ when using this method.
- To understand how it works, let's start by considering a simple example:
 - \Rightarrow Let H be a discrete-time LTI system with impulse response

$$h[n] = 4\delta[n] + 3\delta[n-1] + 2\delta[n-2] + \delta[n-3]$$



- Let the input signal be

$$x[n] = \delta[n+1] + 2\delta[n] + \delta[n-1] - \delta[n-2]$$



→ We could use the simpler "convolution with deltas" method for this problem.

→ But we're not going to do that.

→ Instead, we're going to analyze this example in more detail to develop a greater intuitive understanding of how convolution works.

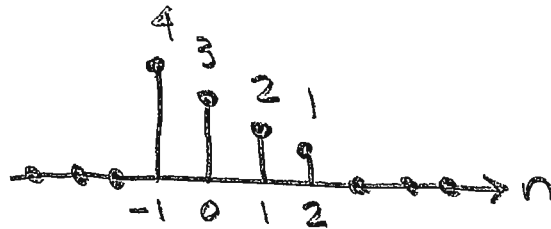
- From linearity, we have that the system output $y[n]$ must be given by

$$\begin{aligned} y[n] &= H\{x[n]\} \\ &= H\{\delta[n+1] + 2\delta[n] + \delta[n-1] - \delta[n-2]\} \\ &= H\{\delta[n+1]\} + 2H\{\delta[n]\} + H\{\delta[n-1]\} - H\{\delta[n-2]\} \end{aligned}$$

- And since H is time invariant, we have that

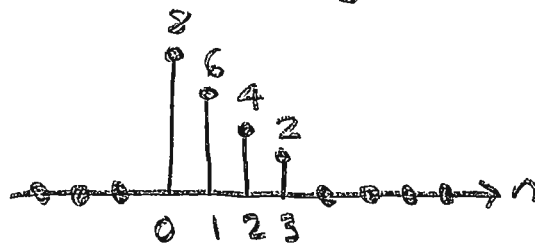
$$y[n] = \underbrace{h[n+1]}_{\text{response due to input term } \delta[n+1]} + \underbrace{2h[n]}_{\text{response due to input term } 2\delta[n]} + \underbrace{h[n-1]}_{\text{response due to input term } \delta[n-1]} - \underbrace{h[n-2]}_{\text{response due to input term } -\delta[n-2]}$$

- So we see that the input term $\delta[n+1]$ arrives at time $n=-1$ and causes a response $h[n+1]$ to start coming out at time $n=-1$:



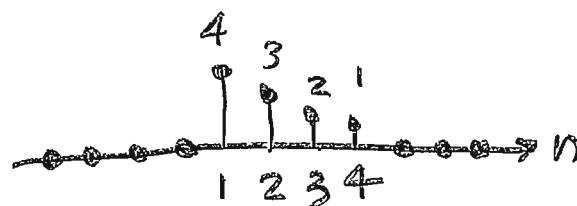
response due to
input at $n=-1$

- The input term $2\delta[n]$ arrives at time $n=0$ and causes a response $2h[n]$ to start coming out at time $n=0$:



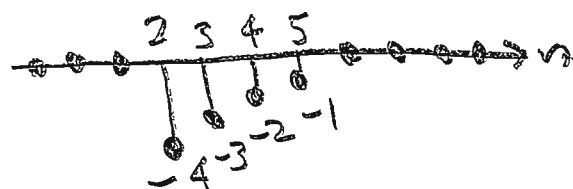
response due to
input at $n=0$

- The input term $\delta[n-1]$ arrives at time $n=1$ and causes a response $h[n-1]$ to start coming out at time $n=1$:



response due to
input at $n=1$

- And finally the input term $-\delta[n-2]$ arrives at time $n=2$ and causes a response $-h[n-2]$ to start coming out at time $n=2$:



response due to
input at $n=2$

- When the signal $x[n]$ is input to the system H , it causes all of these individual responses to come out simultaneously.

- The total response $y[n]$ is the sum of these individual responses.

- Recalling that

$$h[0] = 4$$

$$h[1] = 3$$

$$h[2] = 2$$

$$h[3] = 1$$

and

$$x[-1] = 1$$

$$x[0] = 2$$

$$x[1] = 1$$

$$x[2] = -1$$

→ We can tabulate the individual responses as shown on the next page...

OUTPUT TERMS

Input Terms	n = -1	n = 0	n = 1	n = 2	n = 3	n = 4	n = 5
n = -1 $x[-1] = 1$	$x[-1]h[0] = 4$	$x[-1]h[1] = 3$	$x[-1]h[2] = 2$	$x[-1]h[3] = 1$	0	0	0
n = 0 $x[0] = 2$	0	$x[0]h[0] = 8$	$x[0]h[1] = 6$	$x[0]h[2] = 4$	$x[0]h[3] = 2$	0	0
n = 1 $x[1] = 1$	0	0	$x[1]h[0] = 4$	$x[1]h[1] = 3$	$x[1]h[2] = 2$	1	0
n = 2 $x[2] = -1$	0	0	0	$x[2]h[0] = -4$	$x[2]h[1] = -3$	$x[2]h[2] = -2$	$x[2]h[3] = -1$

At $n=2,$

$x[-1]h[3]$ is still coming out because of the input at $n=-1$
 $x[0]h[2]$ is still coming out because of the input at $n=0$
 $x[1]h[1]$ is still coming out because of the input at $n=1$
 $x[2]h[0]$ just started coming out because of the input at $n=2$

All Together, $y[2] = x[-1]h[3] + x[0]h[2] + x[1]h[1] + x[2]h[0]$

$$= \sum_{k=-\infty}^{\infty} x[k]h[2-k]$$



- To find the number $y[2]$, we have to add up what is coming out at time $n=2$ due to each input term. We get:

The numbers \mapsto

$$(*) \quad y[2] = \underbrace{x[-1]}_1 \cdot \underbrace{h[3]}_1 + x[0] \cdot 2 + 1 \cdot 3 + (-1) \cdot \underbrace{4}_{h[0]}$$

Input term $x[-1]$ was the first to arrive... so the index of his "x" is -1... the smallest. And his "h" has been coming out the longest. So his "h" has the largest index (3).

Input term $x[2]$ was the last to arrive... so his "x" has the largest index (2). But his "h" just started coming out... so he's only on $h[0]$.

\Rightarrow For these individual contributions to the number $y[2]$, we see that the indices of the "x" and "h" go in opposite order



- More generally, the number $y[n]$ is given by

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k] \quad (**)$$

\Rightarrow This loop adds up the contribution to $y[n]$ from every one of the input terms $x[k]$.

- For example, on the $k=-5$ term of the sum, we get

$$\begin{aligned} x[-5] h[2 - (-5)] \\ = x[-5] h[7] \end{aligned}$$

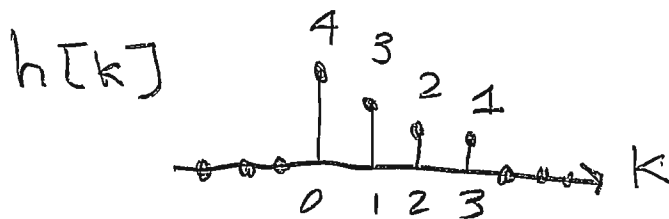
\rightarrow Because the input term $x[-5]$ caused a weighted "h" to start coming out at time $n=-5$, here at time $n=2$ he is up to $x[-5] h[7]$.

- Now, let's make the graph of $h[2-k]$ as a function of the loop counter k ...

- We have $h[2-k] = h[-k - -2]$

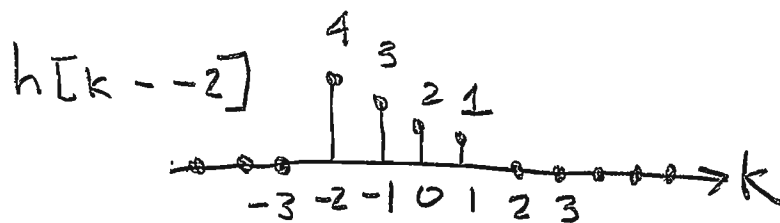
→ There is a shift by -2

→ There is a scale by -1

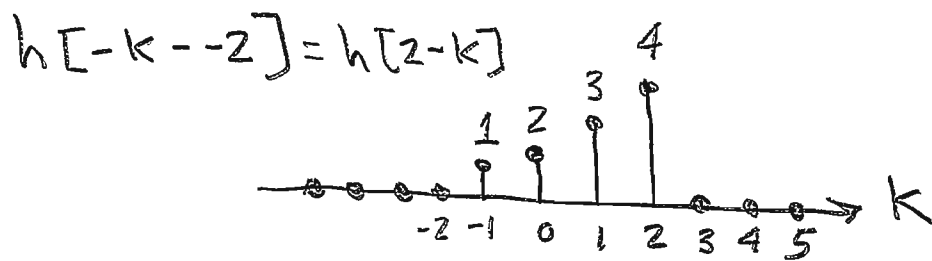


- Do the shift
first

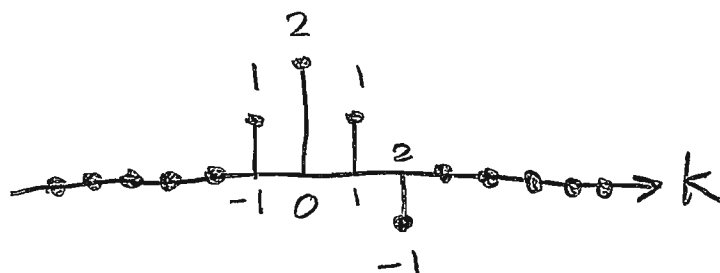
(see page 2.100)



- Then do the
scale

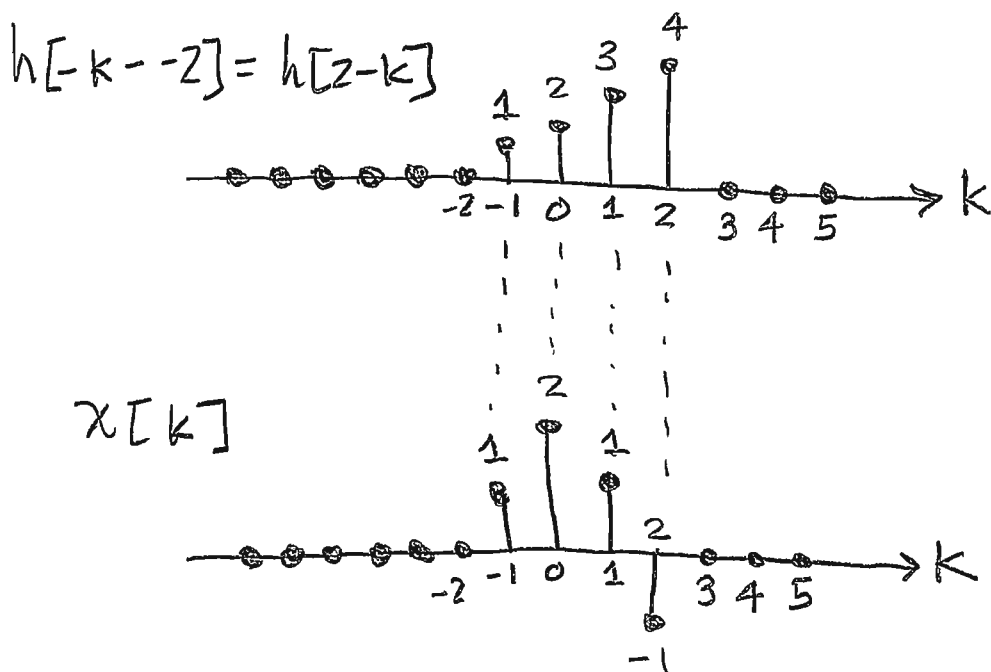


- And here is the graph of $x[k]$: (see page 3.25)



- We now use these graphs from page 3.31 to compute the number $y[2]$ as given in equation $(*)$ on page 3.30:

$$y[2] = \sum_{k=-\infty}^{\infty} x[k] h[2-k]$$



$$y[2] = \underset{x[-1]}{1} \cdot \underset{h[3]}{1} + \underset{x[0]}{2} \cdot \underset{h[2]}{2} + \underset{x[1]}{1} \cdot \underset{h[1]}{3} + \underset{x[2]}{(-1)} \cdot \underset{h[0]}{4} = \underline{\underline{4}}$$

\Rightarrow Compare this to equation $(*)$ on page 3.29...

\Rightarrow They are the same !!

\Rightarrow This exactly adds up what is coming out of the system at time $n=2$ due to each term of the input signal $x[n]$.

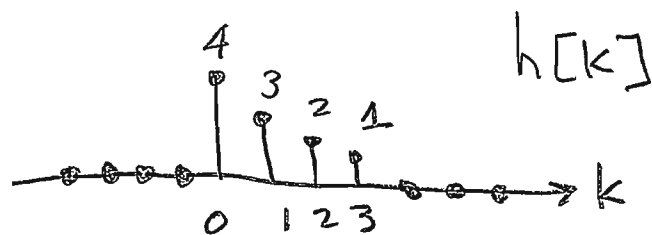
- Now let's see how this works if we compute the convolution the "other way"... i.e. we compute it as (see pages 3.10 and 3.11):

$$\begin{aligned}
 y[n] &= x[n] * h[n] \\
 &= h[n] * x[n] \\
 &= \sum_{k=-\infty}^{\infty} h[k] x[n-k]
 \end{aligned}$$

- Plugging in $n=2$, we get

$$y[2] = \sum_{k=-\infty}^{\infty} h[k] x[2-k]$$

→ here is the graph of $h[k]$:



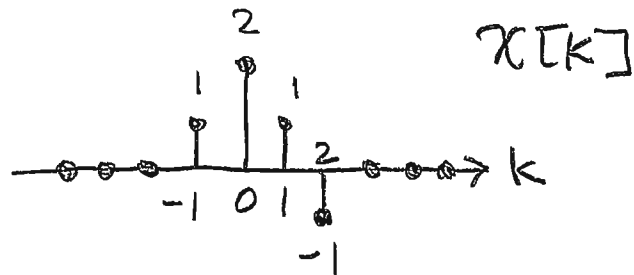
- For $x[2-k]$, we think of it as $x[-k-2]$

- why? Because we are working the do loop on "k"... so we need the graphs as a function of k

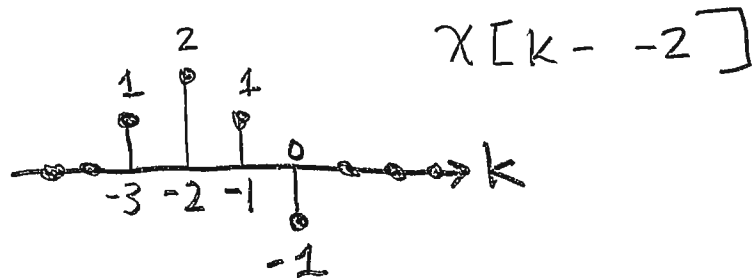
\equiv →

-So, for $x[-k - -2]$ we have a shift by -2 and a scale by -1 .

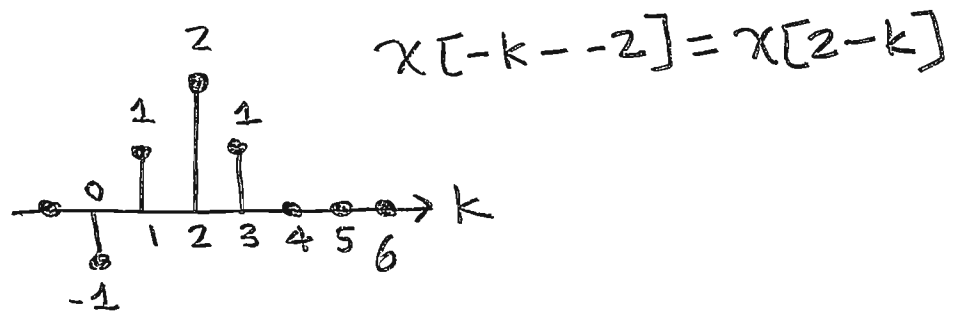
-Following the rule from pages 2.21 and 2.100, we do the shift first, then the scale:



SHIFT
by -2 :

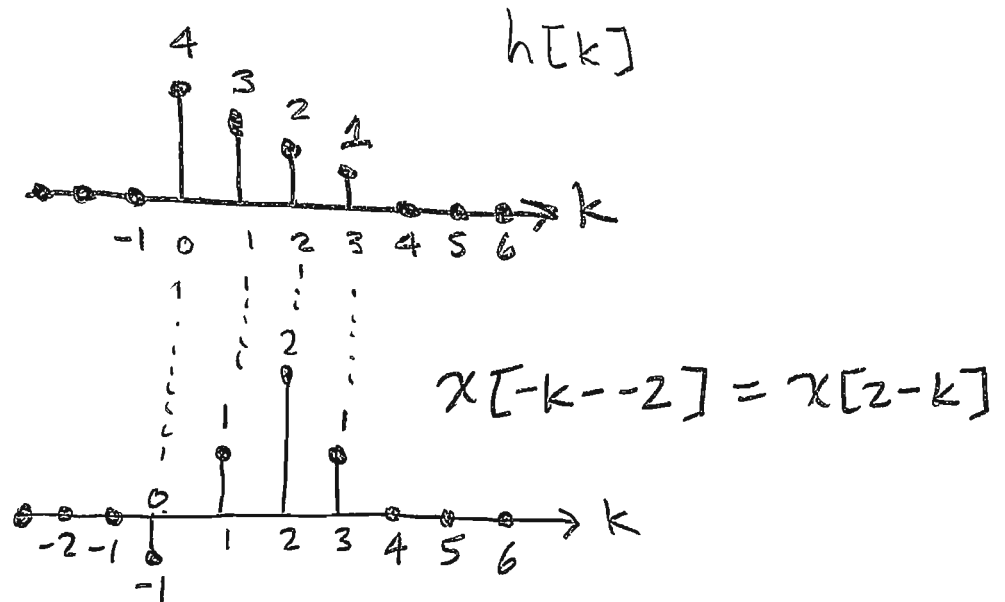


SCALE
by -1 :



- So now let's use the graphs on pages 3.33 & 3.34 to compute the number $y[2]$ according to

$$y[2] = \sum_{k=-\infty}^{\infty} h[k] x[2-k]$$



$$y[2] = (-1) \cdot 4 + 1 \cdot 3 + 2 \cdot 2 + 1 \cdot 1 = \underline{\underline{4}}$$

$x[2]$ $h[0]$ $x[1]$ $h[1]$ $x[0]$ $h[2]$ $x[-1]$ $h[3]$

→ It's exactly the same thing we got before on p. 3.32 and p. 3.29

→ It adds up what is coming out of the system at $n=2$ due to each term of the input signal $x[n]$.

⇒ But compared to how we did it on p. 3.32, this way adds up the individual terms in backwards order.

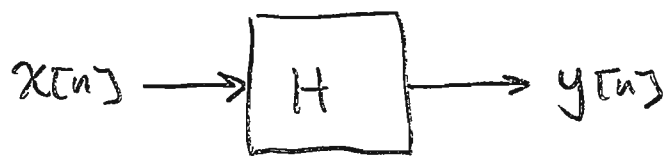
SUMMARY :

- On pages 3.24 and 3.25, we had an LTI system H with impulse response

$$h[n] = 4\delta[n] + 3\delta[n-1] + 2\delta[n-2] + \delta[n-3]$$

- The input was (page 3.25)

$$x[n] = \delta[n+1] + 2\delta[n] + \delta[n-1] - \delta[n-2]$$



- On pages 3.30 - 3.32, we computed the number $y[2]$ using the formula

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

\Rightarrow we got $y[2] = 4$.

- On pages 3.33 - 3.35, we computed the same number $y[2]$ using the formula

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k]$$

\Rightarrow we again got $y[2] = 4$ ✓

- In general, to find the whole signal $y[n]$, we have to do this for every n .

⇒ This is called graphical convolution.

- However, there is good news:

- usually we don't have to do every n individually.

- usually we can do the n 's in batches.

⇒ In other words, usually we can find just a few expressions for $y[n]$, where each expression is good for a whole batch of n 's.

- In most books, these expressions, each one good for a whole batch of n 's, are called "regions" or "cases".

☆☆ HOW TO PERFORM GRAPHICAL CONVOLUTION ON A TEST WITHOUT MAKING MISTAKES

Given: H is a discrete-time LTI system with impulse response $h[n]$ (given) and input signal $x[n]$ (given).

Find: the output signal $y[n]$.

① choose which signal gets the "k" and which one gets the "n-k", i.e.

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

OR

$$y[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

→ you can always get the right answer either way. But one way might be slightly easier to work out.

→ usually it's best to pick the one with the simpler expression to get the "n-k".

⇒ For the following steps, assume we picked the first way... i.e., $x[k]$ and $h[n-k]$.

② Make a graph of $x[k]$.

③ Make a graph of $h[n-k]$... as a function of k .

→ To avoid making mistakes, always do this in three steps:

③A Graph $h[k]$

③B Shift the graph in ③A to the right by $-n$ to obtain the graph of $h[k - (-n)] = h[n+k]$

③C Flip the graph in ③B with respect to the k -axis to obtain the graph of $h[-k - (-n)] = h[n-k]$.

④ To find $y[n]$, you must multiply the graphs in ② and ③C pointwise and then add up the product graph from $k=-\infty$ to $k=+\infty$.

⇒ The product graph generally depends on "n".

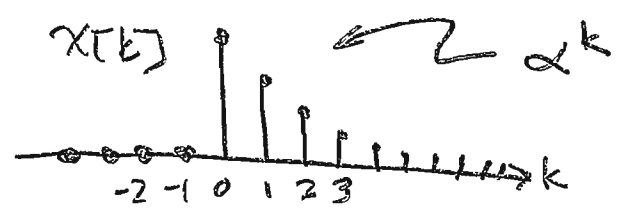
→ you will see that different batches of n's result in different limits for the sum.

→ These different batches are the so-called "cases" or "regions"!

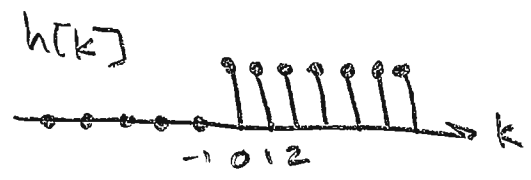
EX: $x[n] = \alpha^n u[n]$, $0 < \alpha < 1$ (for example, α could be $1/2$)
 $h[n] = u[n]$

→ since $x[n]$ has the more complicated expression, we will put the "k" on x and the "n-k" on h .

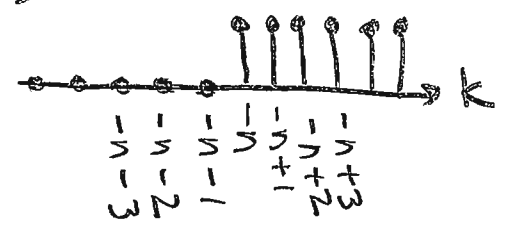
- Graph $x[k]$:



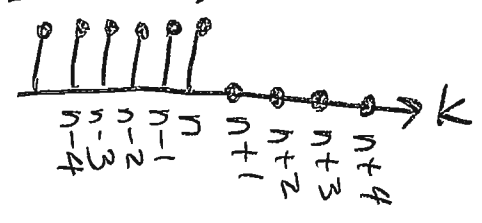
- Graph $h[n-k]$ in three steps:



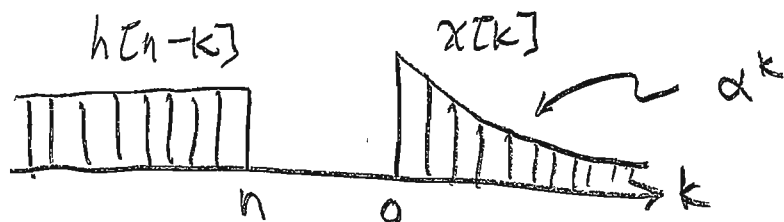
$h[k-n] = h[n+k]$



$h[-k-n] = h[n-k]$

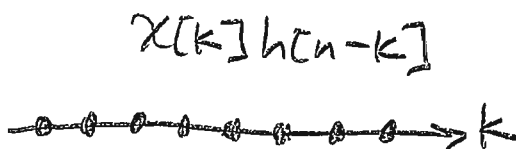


- When $n < 0$, we have:



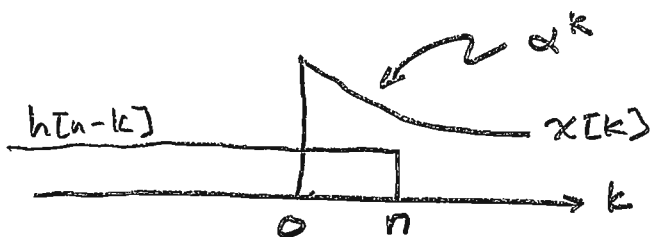
- When $n \leq 0$, for every k either $x[k] = 0$ or $h[n-k] = 0$.

- So the product graph is all zeros when $n < 0$.



- So $y[n] = \sum_{k=-\infty}^{\infty} 0 = 0$ when $n < 0$.

- When $n \geq 0$, we have:



→ In this case ($n \geq 0$), the product graph is nonzero from $k=0$ to $k=n$

→ In this range of k 's, we have $x[k] = \alpha^k$ and $h[n-k] = 1$



- So, when $n \geq 0$ the product graph looks like this:



- We get

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$= \sum_{k=0}^n \alpha^k$$

$$= \frac{\alpha^0 - \alpha^{n+1}}{1 - \alpha} \quad (\text{sum formula})$$

$$= \frac{1 - \alpha^{n+1}}{1 - \alpha}$$

- For this problem, these two cases cover all of the n 's.

- So, putting them together, the answer is:

$$y[n] = \begin{cases} 0, & n < 0 \\ \frac{1 - \alpha^{n+1}}{1 - \alpha}, & n \geq 0 \end{cases}$$

$$= \frac{1 - \alpha^{n+1}}{1 - \alpha} u[n]$$



- Now let's work that same problem the other way... to show that we will get the same answer.
- And let's write it the way we would on a test!!

$$x[n] = \alpha^n u[n], \quad h[n] = u[n]$$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

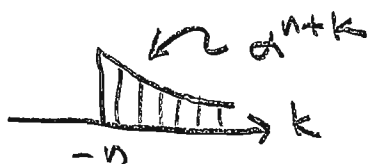
$h[k]$



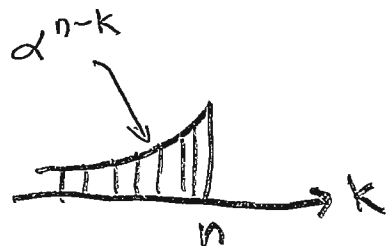
$x[k]$



$$x[k-n] = x[n+k]$$



$$x[-k-n] = x[n-k]$$

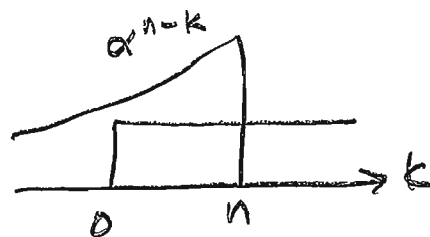


Case I) $n < 0$



$$y[n] = \sum_{k=-\infty}^{\infty} 0 = 0$$

Case II) $n \geq 0$



$$y[n] = \sum_{k=0}^n \alpha^{n-k} \cdot 1 = \sum_{k=0}^n \alpha^n \alpha^{-k}$$

$$= \alpha^n \sum_{k=0}^n \alpha^{-k} = \alpha^n \sum_{k=0}^n \left(\frac{1}{\alpha}\right)^k$$

$$= \alpha^n \frac{\left(\frac{1}{\alpha}\right)^0 - \left(\frac{1}{\alpha}\right)^{n+1}}{1 - \frac{1}{\alpha}}$$

$$= \alpha^n \frac{1 - \alpha^{-n-1}}{1 - \alpha^{-1}} \cdot \frac{\alpha}{\alpha} \quad \left. \begin{matrix} \alpha \\ \alpha \end{matrix} \right\} \text{one}$$

$$= \alpha^n \frac{\alpha - \alpha^{-n}}{\alpha - 1} = \frac{\alpha^{n+1} - 1}{\alpha - 1} \cdot \frac{-1}{-1} \quad \left. \begin{matrix} -1 \\ -1 \end{matrix} \right\} \text{one}$$

$$= \frac{1 - \alpha^{n+1}}{1 - \alpha}$$

→

All Together :

$$y[n] = \begin{cases} 0, & n < 0 \\ \frac{1 - \alpha^{n+1}}{1 - \alpha}, & n \geq 0 \end{cases} \\ = \frac{1 - \alpha^{n+1}}{1 - \alpha} u[n] \quad \text{// //}$$

\Rightarrow SAME answer as we got doing it the first way.

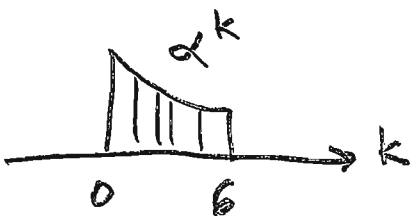
EX :

$$x[n] = \begin{cases} 1, & 0 \leq n \leq 4 \\ 0, & \text{otherwise} \end{cases} = u[n] - u[n-5]$$

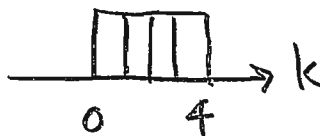
$$h[n] = \begin{cases} \alpha^n, & 0 \leq n \leq 6 \\ 0, & \text{otherwise} \end{cases} = \alpha^n \{u[n] - u[n-7]\} \\ 0 < \alpha < 1$$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

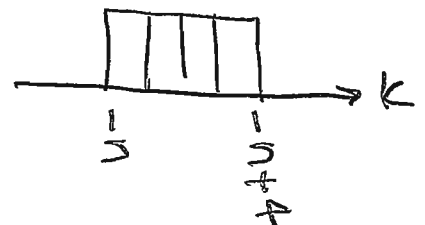
$h[k]$



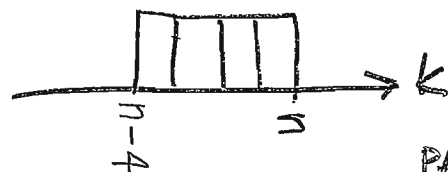
$x[k]$



$x[k-n] = x[n+k]$

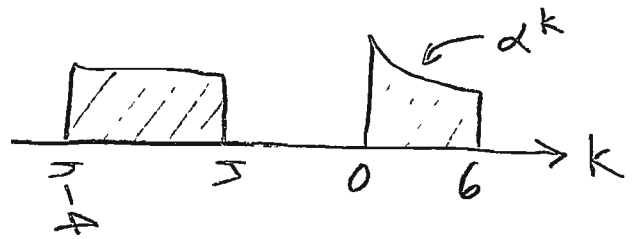


$x[-k-n] = x[n-k]$



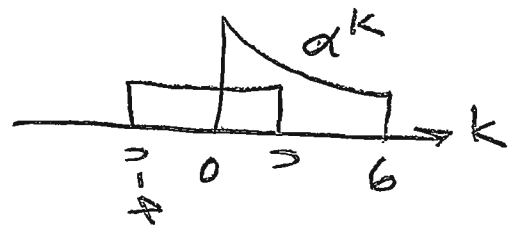
Case I) $n < 0$;

$$y[n] = \sum_{k=-\infty}^{\infty} 0 = 0$$



Case II) $n \geq 0$ and $n-4 < 0$; $0 \leq n < 4$

- The product graph has something in it from $k=0$ to $k=n$



→ In other words, the product graph is "turned on" from $k=0$ to $k=n$.

→ $h[k]$ turns it on at $n=0$

→ $x[n-k]$ turns it off after $k=n$

NOTE : any time there is a change in who turns it on and who turns it off, it will signal the start of a new region or "case".

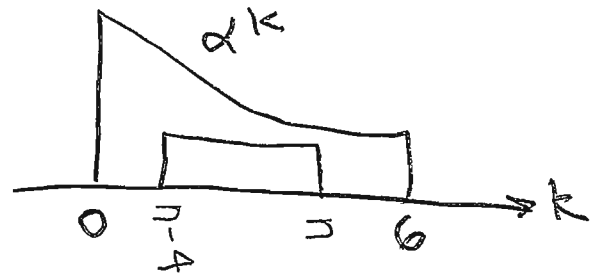
- here in case II, we have:

$$y[n] = \sum_{k=0}^n \alpha^k \cdot 1 = \sum_{k=0}^n \alpha^k = \frac{\alpha^0 - \alpha^{n+1}}{1 - \alpha}$$

$$= \frac{1 - \alpha^{n+1}}{1 - \alpha}$$

Case III) $n-4 > 0$ and $n < 6$: $4 \leq n < 6$:

- In this case, $x[n-k]$ turns the product graph on at $k=n-4$,



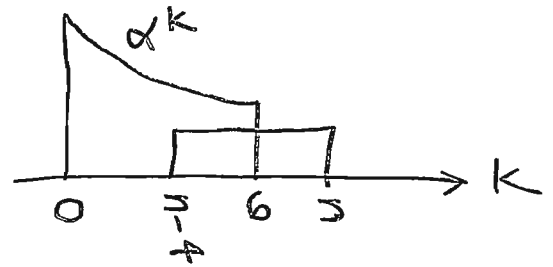
- And $x[n-k]$ also turns the product graph off after $k=n$ (i.e., the product graph is zero starting at $k=n+1$).

$$y[n] = \sum_{k=n-4}^n \alpha^k = \frac{\alpha^{n-4} - \alpha^{n+1}}{1-\alpha}$$

Case IV) $n > 6$ and $n-4 < 7$: $6 \leq n < 11$

- In this case, $x[n-k]$ turns the product graph on at $k=n-4$

- $h[k]$ turns the product graph off for $k > 6$

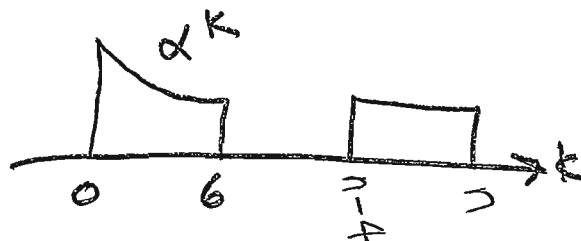


$$y[n] = \sum_{k=n-4}^6 \alpha^k = \frac{\alpha^{n-4} - \alpha^7}{1-\alpha}$$



Case II) $n-4 \gg 7$: $n \gg 11$:

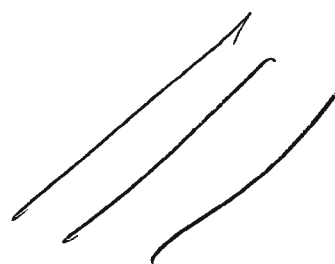
→ The product graph is all zeros



$$y[n] = \sum_{k=-\infty}^{\infty} 0 = 0$$

All Together :

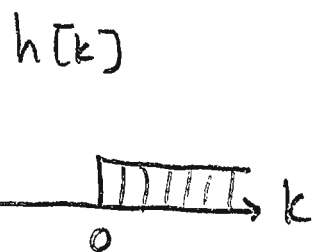
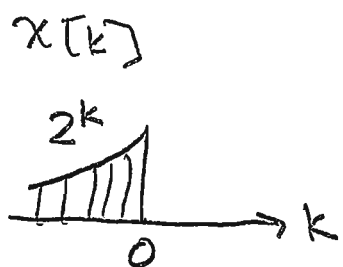
$$y[n] = \left\{ \begin{array}{ll} 0 & , \quad n < 0 \\ \frac{1 - \alpha^{n+1}}{1 - \alpha} & , \quad 0 \leq n < 4 \\ \frac{\alpha^{n-4} - \alpha^{n+1}}{1 - \alpha} & , \quad 4 \leq n < 6 \\ \frac{\alpha^{n-4} - \alpha^7}{1 - \alpha} & , \quad 6 \leq n < 11 \\ 0 & , \quad n \gg 11 \end{array} \right.$$



EX : $x[n] = 2^n u[-n]$

$h[n] = u[n]$

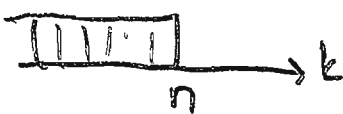
$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$



$h[k--n] = h[n+k]$



$h[-k--n] = h[n-k]$

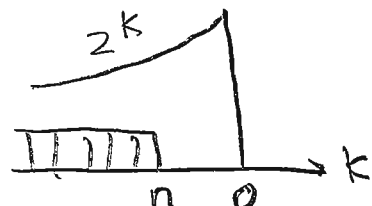


Case I) $n < 0$

$y[n] = \sum_{k=-\infty}^n 2^k$

$= \lim_{A \rightarrow \infty} \sum_{k=-A}^n 2^k = \lim_{A \rightarrow \infty} \frac{2^{-A} - 2^{n+1}}{1-2}$

$= \lim_{A \rightarrow \infty} \frac{(\frac{1}{2})^A - 2^{n+1}}{-1} = \frac{0 - 2^{n+1}}{-1} = 2^{n+1}$

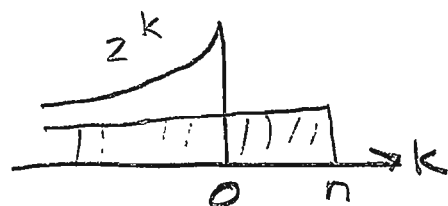


Case II) $n \geq 0$

$y[n] = \sum_{k=-\infty}^0 2^k$

$= \lim_{A \rightarrow \infty} \sum_{k=-A}^0 2^k = \lim_{A \rightarrow \infty} \frac{2^{-A} - 2^1}{1-2}$

$= \lim_{A \rightarrow \infty} \frac{(\frac{1}{2})^A - 2}{-1} = \frac{0 - 2}{-1} = 2$



All Together :

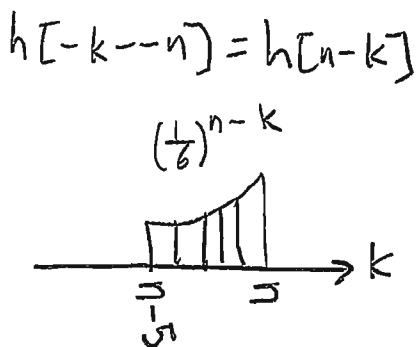
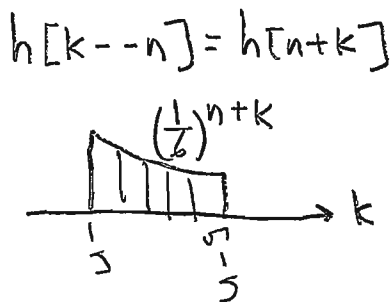
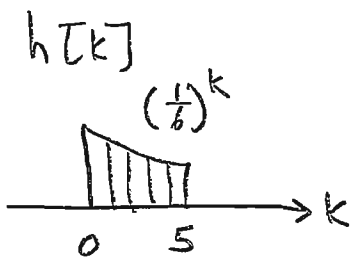
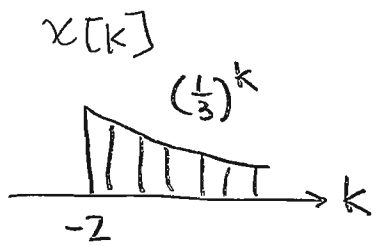
$y[n] = \begin{cases} 2^{n+1} & , n < 0 \\ 2 & , n \geq 0 \end{cases}$



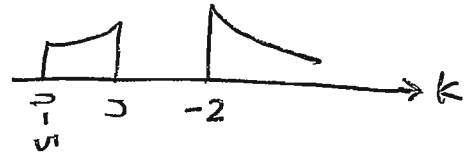
EX: $x[n] = \left(\frac{1}{3}\right)^n u[n+2]$

$$h[n] = \left(\frac{1}{6}\right)^n \{u[n] - u[n-6]\} = \begin{cases} \left(\frac{1}{6}\right)^n, & 0 \leq n \leq 5 \\ 0, & \text{otherwise} \end{cases}$$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$



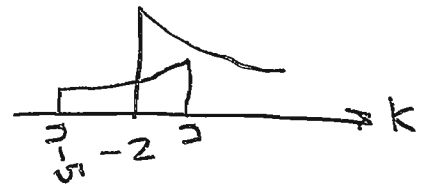
Case I) $n < -2$



$$y[n] = \sum_{k=-\infty}^{\infty} 0 = 0$$

Case II) $n > -2$ and $n-5 < -2$: $-2 \leq n < 3$

$$y[n] = \sum_{k=-2}^n \left(\frac{1}{3}\right)^k \left(\frac{1}{6}\right)^{n-k}$$



$$= \sum_{k=-2}^n \left(\frac{1}{3}\right)^k \left(\frac{1}{6}\right)^n \left(\frac{1}{6}\right)^{-k}$$

$$= \left(\frac{1}{6}\right)^n \sum_{k=-2}^n \left(\frac{1}{3}\right)^k 6^k = \left(\frac{1}{6}\right)^n \sum_{k=-2}^n 2^k$$

$$= \left(\frac{1}{6}\right)^n \frac{2^{-2} - 2^{n+1}}{1-2} = \left(\frac{1}{6}\right)^n \frac{\frac{1}{4} - 2 \cdot 2^n}{-1}$$

$$= \left(\frac{1}{6}\right)^n \frac{2 \cdot 2^n - \frac{1}{4}}{1} = 2 \left(\frac{1}{6}\right)^n 2^n - \frac{1}{4} \left(\frac{1}{6}\right)^n$$

$$= 2 \left(\frac{1}{3}\right)^n - \frac{1}{4} \left(\frac{1}{6}\right)^n$$



Case III) $n-5 \geq -2 : n \geq 3$

$$y[n] = \sum_{k=n-5}^n \left(\frac{1}{3}\right)^k \left(\frac{1}{6}\right)^{n-k}$$

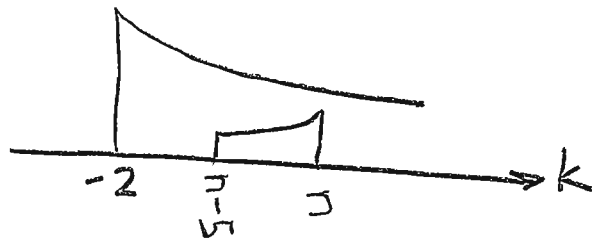
$$= \sum_{k=n-5}^n \left(\frac{1}{3}\right)^k \left(\frac{1}{6}\right)^n \left(\frac{1}{6}\right)^{-k}$$

$$= \left(\frac{1}{6}\right)^n \sum_{k=n-5}^n \left(\frac{1}{3}\right)^k 6^k = \left(\frac{1}{6}\right)^n \sum_{k=n-5}^n 2^k$$

$$= \left(\frac{1}{6}\right)^n \frac{2^{n-5} - 2^{n+1}}{1-2} = \left(\frac{1}{6}\right)^n \frac{2^n 2^{-5} - 2 \cdot 2^n}{-1}$$

$$= \left(\frac{1}{6}\right)^n \left[2 \cdot 2^n - \left(\frac{1}{32}\right) 2^n \right] = \left(\frac{1}{6}\right)^n 2^n \left[2 - \frac{1}{32} \right]$$

$$= \left(\frac{2}{6}\right)^n \left[\frac{64}{32} - \frac{1}{32} \right] = \frac{63}{32} \left(\frac{1}{3}\right)^n$$



All Together:

$$y[n] = \begin{cases} 0 & , \quad n < -2 \\ 2 \left(\frac{1}{3}\right)^n - \frac{1}{4} \left(\frac{1}{6}\right)^n & , \quad -2 \leq n < 3 \\ \frac{63}{32} \left(\frac{1}{3}\right)^n & , \quad n \geq 3 \end{cases}$$



MORE ON HOW TO FIND THE "REGIONS" OR "CASES"

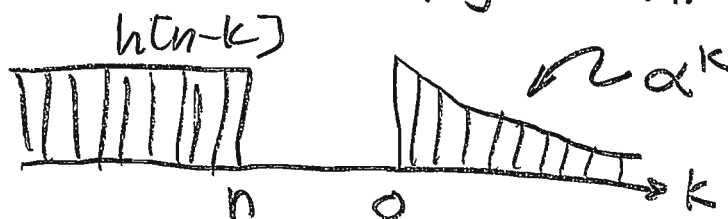
$$x[n] \rightarrow \boxed{H} \rightarrow y[n] = x[n] * h[n]$$

- To solve for the output signal, we have to say what the number $y[n]$ is for every n .
- For each n , the number $y[n]$ is given by the sum of the product graph:

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

- For any particular problem, $x[n]$ and $h[n]$ will be given... and the product graph will look different for different batches of n 's.

⇒ More specifically, there may be batches of n 's where the product graph has nothing in it and $y[n]=0$... as we saw, e.g., on page 3.41.



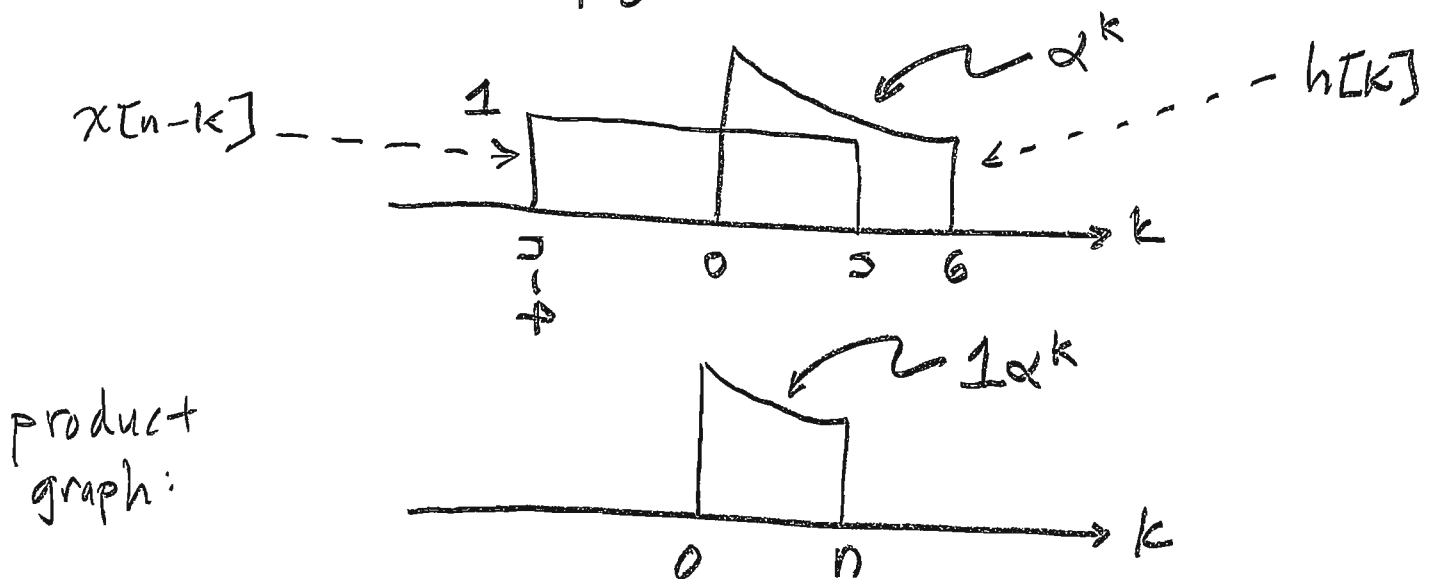
→ product graph is all zeros.

⇒ For other batches of n 's, the product graph will have something in it...

⇒ And to find $y[n]$ for these n 's, we have to add up what's in the product graph.

⇒ The limits of the sum are determined by who turns the product graph on ... and who turns the product graph off.

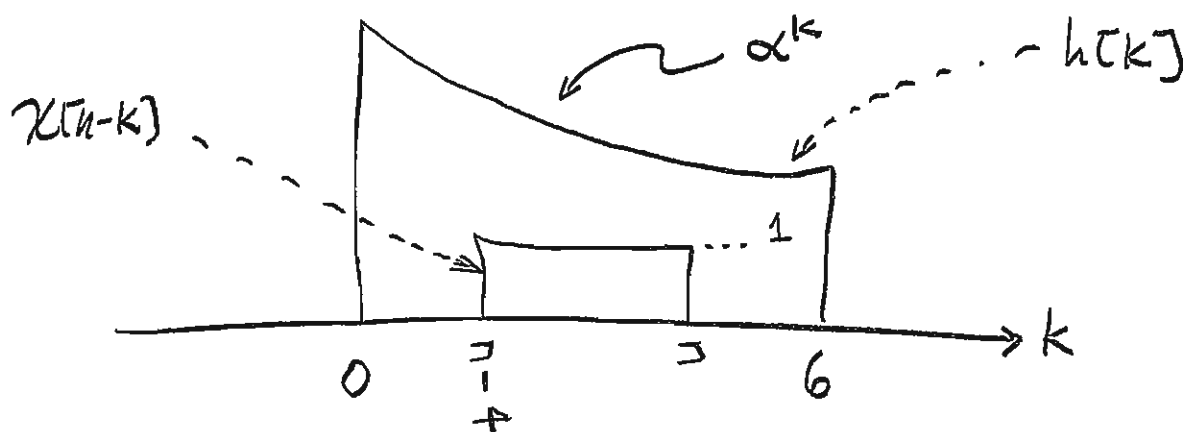
EX: case II from page 3.45:



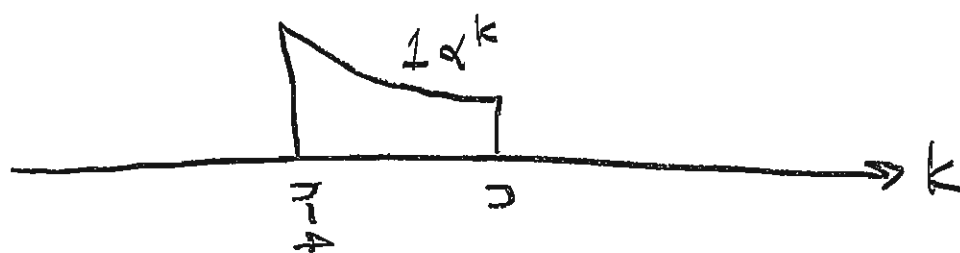
→ $h[k]$ turns it on at $k=0$.

→ $x[n-k]$ turns it off after $k=n$.

EX: Case III from page 3.46:



product graph:



→ $x[n-k]$ turns it on at $k=n-4$

→ And $x[n-k]$ also turns it off after $k=n$.

- To find $y[n]$, you must consider all of the n 's...
you must find $y[n] \forall n \in \mathbb{Z}$.

- Start by considering gigantically negative n 's...
like $n = -10^{40}$. Figure out what the product graph looks like... and what are the limits of the sum (i.e., who turns it on and who turns it off).



- Now consider larger and larger values of n .

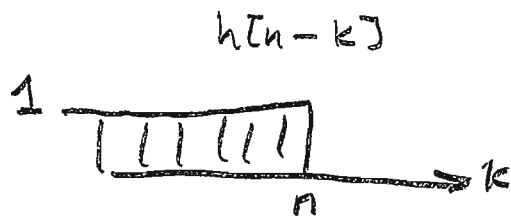
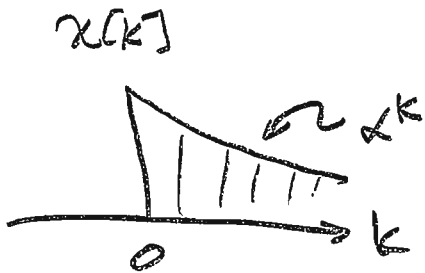
⇒ Any time there is a change in who turns it on and/or who turns it off, it changes the limits of the sum...

⇒ This means that you have hit the start of a new region.

- You must continue in this way until you have done all of the n 's.

- Let's re-examine the first example from page 3.40 and pay more attention to how the regions are determined.

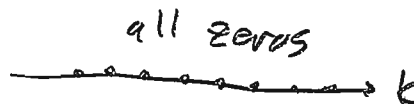
- We've got:



→ When n is gigantically negative, these graphs don't overlap... and so the product graph is all zeros for the gigantically negative n 's:



product graph:



→ So this is our first "region": nobody turns it on and nobody turns it off.

⇒ Case I) $y[n] = 0$

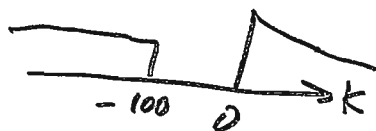


- How long is this good for?

→ In other words, what n 's are included in case I?

→ It starts at $n = -\infty$.

→ When $n = -100$, we've still got



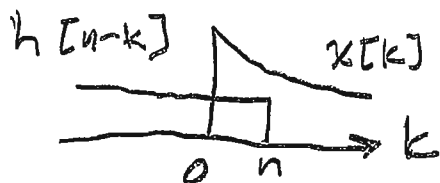
- nobody turns it on, nobody turns it off

→ when $n = -1$, we've still got



- nobody turns it on, nobody turns it off

⇒ but when $n = 0, 1, 2, 3 \dots$ things change



→ starting with $n = 0$, the product graph has something in it.

→ Because, starting with $n = 0$,

⇒ $x[k]$ turns it on at $k = 0$.

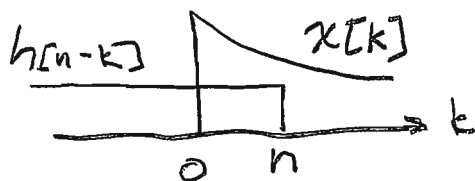
⇒ $h[n-k]$ turns it off after $k = n$.

\Rightarrow So the last n that's included in case I
 (the "nobody turns it on, nobody turn it off" case)
 is $n = -1$.

\Rightarrow Case I is for n 's going $-\infty$ to -1 .

\Rightarrow Case I is $n < 0$.

- Starting with $n = 0$, we are in a new
 case or "region" (Case II) where $x[k]$
 turns it on and $h[n-k]$ turns it off:



product graph:



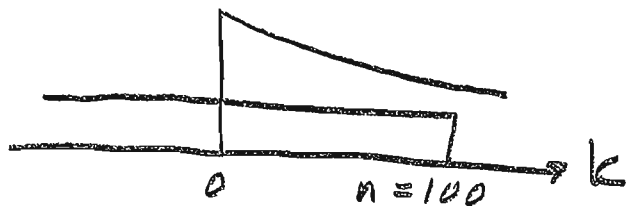
$$\begin{aligned}
 y[n] &= \sum_{k=0}^n x[k] h[n-k] \\
 &= \sum_{k=0}^n \alpha^k
 \end{aligned}$$

- How long is this good for?

→ In other words, case II starts with $u=0$, but how far does it go?

⇒ case II is where $x[k]$ turns the product graph on at $k=0$ and $h[n-k]$ turns the product graph off after $k=n$.

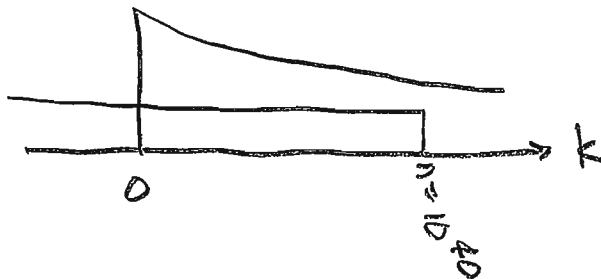
- when $n=100$, we have



⇒ still the same

$$y[n] = \sum_{k=0}^n \alpha^k$$

- when $n=10^{40}$, we have



⇒ still the same

$$y[n] = \sum_{k=0}^n \alpha^k$$

- So Case II is good for all the rest of the n's.

⇒ We've got:

Case I) $n < 0$

Case II) $n > 0$

⇒ This takes care of all the n's.

⇒ So there are only two cases (or regions) in this problem.

- On page 3.42, we got the answer for $y[n]$ as

$$y[n] = \begin{cases} 0 & , n < 0 \quad \leftarrow \text{Case I} \\ \frac{1 - \alpha^{n+1}}{1 - \alpha} & , n > 0 \quad \leftarrow \text{Case II} \end{cases}$$

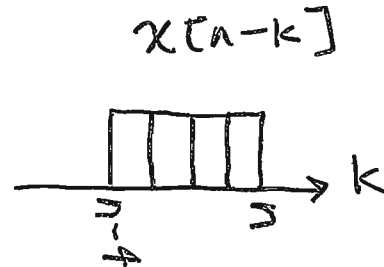
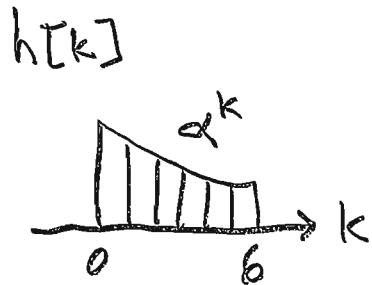
⇒ Notice that our answer says what $y[n]$ is for all of the n's. ~~***~~

⇒ Your answer must include cases that cover all of the n's.

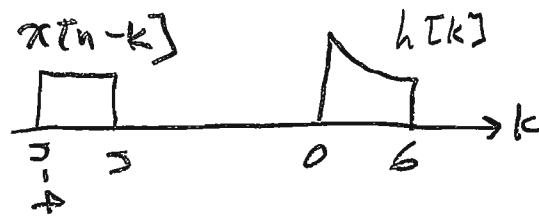
⇒ In other words, every n must be included in one of your cases. ~~***~~

- Now let's take another look at the example that started on page 3.44... and pay special attention to how we determine the "regions."

- At the bottom of page 3.44, we got



→ Start with the gigantically negative n's... like $n = -10^{40}$:



→ The product graph is all zeros.

→ $y[n] = 0$

→ As in the last example, this case is for "nobody turns it on, nobody turns it off."

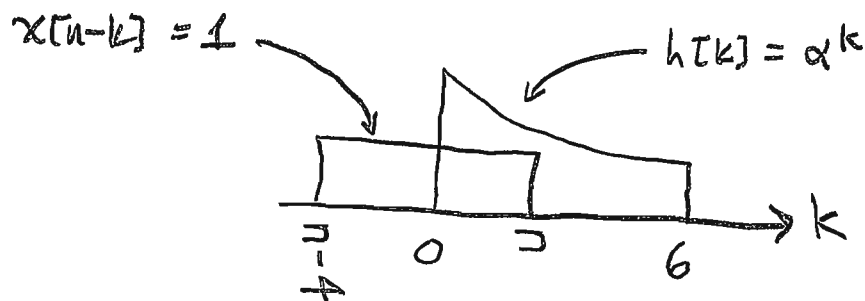
→ This is good for $n = -10^{40}$, $n = -100$, and $n = -1$.

→ But, at $n = 0$ things change!

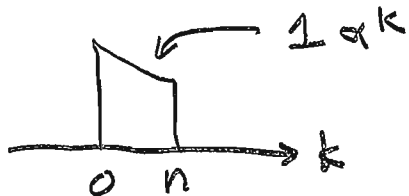
⇒ So: case I) $n < 0$



- Starting at $n=0$, we get into a new case where the product graph has something in it.



product graph:



- $h[k]$ turns the product graph on at $k=0$.
- $x[n-k]$ turns the product graph off after $k=n$.

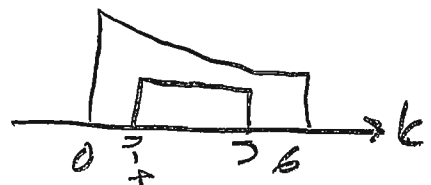
⇒ we've got

$$y[n] = \sum_{k=0}^n \alpha^k \quad (\text{case II})$$

→ How long is this good for?

- Well, when $n-4=0$ (i.e., when $n=4$), things change!

- Starting at $n-4=0$, we get that $x[n-k]$ turns the product graph on and $x[n-k]$ turns the product graph off:



- So, starting at $n=4$ we are in a new region (case III).

- So case II is for: $n > 0$ and $n-4 < 0$

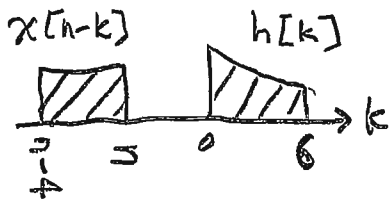
$$\Rightarrow 0 \leq n < 4 \quad \text{///}$$

\Rightarrow And case III starts with $n=4$.

- We have to continue in this way until we have covered all of the n 's.

\Rightarrow For this problem, we get the following cases:

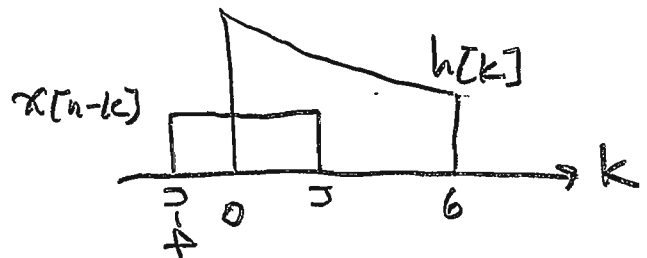
Case I) $n < 0$:



\rightarrow Nobody turns the product graph on, nobody turns the product graph off.

Case II) $n > 0$ and $n-4 < 0$

$$0 \leq n < 4$$



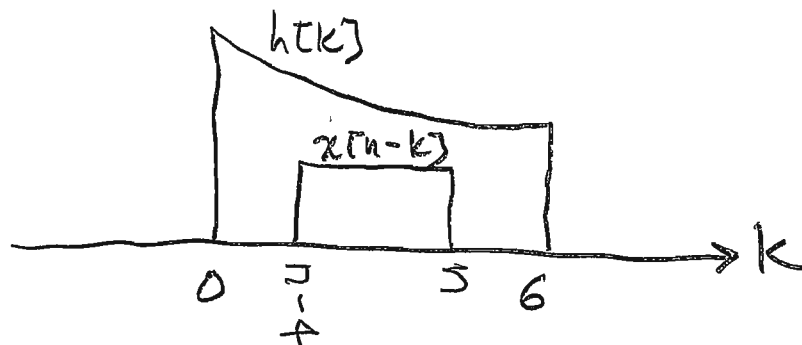
\rightarrow $h[k]$ turns the product graph on at $k=0$.

\rightarrow $x[n-k]$ turns the product graph off after $k=n$.

$$y[n] = \sum_{k=0}^n \alpha^k$$



Case III) $n-4 \geq 0$ and $n < 6$: $4 \leq n < 6$



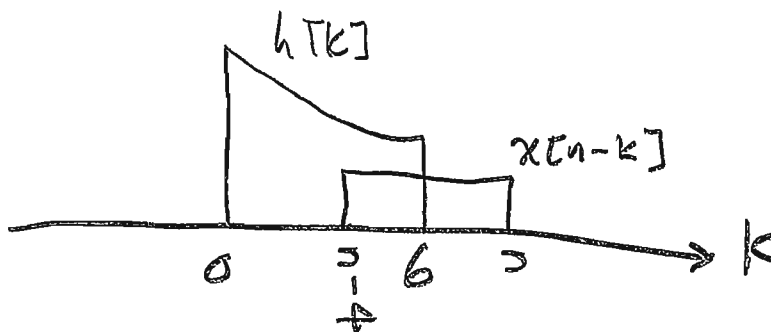
→ $x[n-k]$ turns the product graph on at $k=n-4$.

→ $x[n-k]$ turns the product graph off after $k=n$.

$$y[n] = \sum_{k=n-4}^n \alpha^k$$

Case IV) $n > 6$ and $n-4 < \underline{\underline{7}}$: $6 \leq n < 11$

Same as
 $n-4 \leq 6$



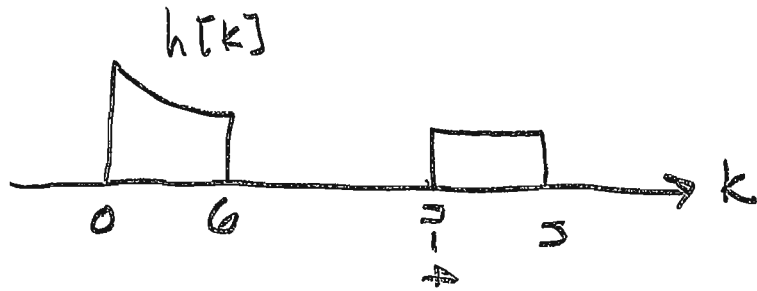
- $x[n-k]$ turns the product graph on at $k=n-4$

- $h[k]$ turns the product graph off after $k=6$

$$y[n] = \sum_{k=n-4}^6 \alpha^k$$

→

Case V) $n-4 \geq 7$; $n \geq 11$



→ Nobody turns the product graph on.
→ Nobody turns the product graph off.

⇒ The product graph is once again all zeros.

years = 0

- As in our final answer on page 3.47, our cases for this problem are:

Case I) $n < 0$

Case II) $0 \leq n < 4$

Case III) $4 \leq n < 6$

Case IV) $6 \leq n < 11$

Case V) $n \geq 11$

⇒ All of the n's are covered.

⇒ Every n is included in one of our cases.

A Note About the Boundary Points Between

the Cases:

- Let's take another closer look at the example we have been analyzing.

- It's:

$$x[n] = \begin{cases} 1, & 0 \leq n \leq 4 \\ 0, & \text{otherwise} \end{cases} = u[n] - u[n-5]$$

$$h[n] = \begin{cases} \alpha^n, & 0 \leq n \leq 6 \\ 0, & \text{otherwise} \end{cases} = \alpha^n \{u[n] - u[n-7]\}$$

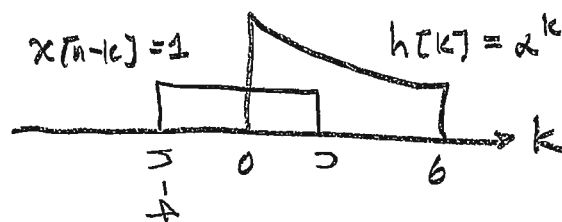
⇒ we just analyzed the "regions" or "cases" for this problem on pages 3.60 - 3.64

⇒ we also solved it on pages 3.44 - 3.47.

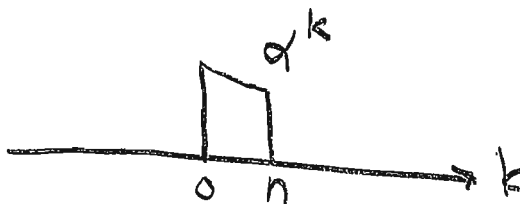
→ The answer we got for $y[n]$ on page 3.47 was

$$y[n] = \begin{cases} 0 & , n < 0 \\ \frac{1 - \alpha^{n+1}}{1 - \alpha} & , 0 \leq n < 4 \\ \frac{\alpha^{n+4} - \alpha^{n+1}}{1 - \alpha} & , 4 \leq n < 6 \\ \frac{\alpha^{n+4} - \alpha^7}{1 - \alpha} & , 6 \leq n < 11 \\ 0 & , n \geq 11 \end{cases}$$

- On page 3.45 and on page 3.61, we saw that case II for this problem looks like:



product graph:

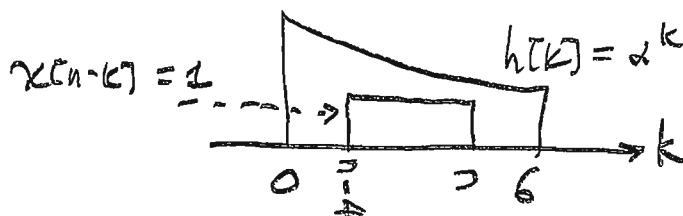


→ $h[k]$ turns the product graph on at $k=0$.
 → $x[n-k]$ turns the product graph off after $k=n$.

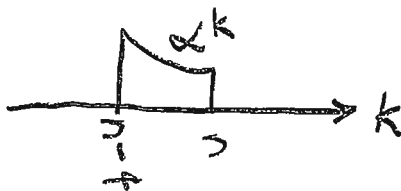
$$y[n] = \sum_{k=0}^n \alpha^k = \frac{1 - \alpha^{n+1}}{1 - \alpha} \quad (\text{case II})$$

⇒ When $n-4=0 \dots$ so that $n=4$, we considered it to be the start of Case III.

- on pages 3.46 and 3.63, we set up Case III as:



product graph:



→ $x[n-k]$ turns the product graph on at $k=n-4$.
 → $x[n-k]$ turns the product graph off after $k=n$.

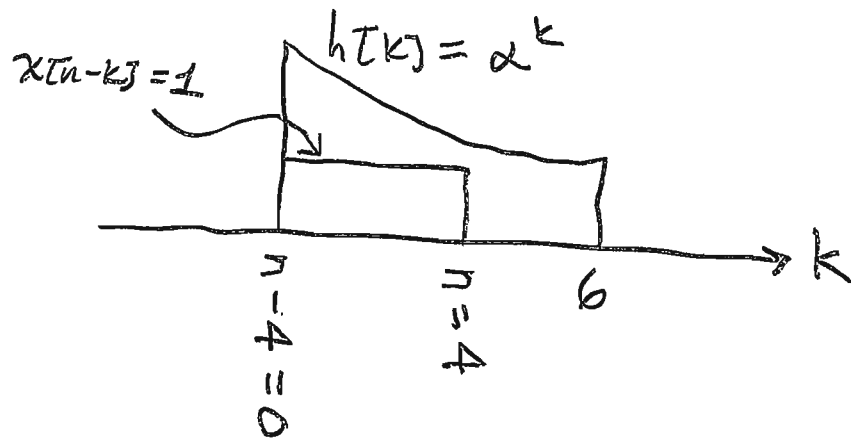
$$y[n] = \sum_{k=n-4}^n \alpha^k = \frac{\alpha^{n-4} - \alpha^{n+1}}{1 - \alpha}$$



- But now lets consider the "n" value that is right on the boundary between these two regions...

- It is when $n-4=0$, or $n=4$.

- For $n=4$, the picture looks like this:



\Rightarrow From this picture, it's clear that we can consider $n=4$ to be the first time that $x[n-k]$ turns the product graph on at $k=n-4$... as we did on pages 3.46 and 3.63...

\Rightarrow OR we can consider $n=4$ to be the last time that $h[k]$ turns the product graph on at $k=0$ (since $n-4=0$ when $n=4$)

\Rightarrow Either way is correct \longrightarrow

- In other words, we can consider the boundary point $n=4$ to be the last "n" in case II...

- or we can consider it to be the first "n" in case III.

- But does either way really work??

⇒ If we put $n=4$ in case II, then we are saying that $y[4]$ should use the case II formula.

→ We get

$$y[4] = \left. \frac{1 - \alpha^{n+1}}{1 - \alpha} \right|_{n=4} = \frac{1 - \alpha^5}{1 - \alpha}$$

⇒ If we put $n=4$ in case III instead, then we are saying that $y[4]$ should use the case III formula instead... we get

$$y[4] = \left. \frac{\alpha^{n-4} - \alpha^{n+1}}{1 - \alpha} \right|_{n=4} = \frac{\alpha^0 - \alpha^5}{1 - \alpha} = \frac{1 - \alpha^5}{1 - \alpha}$$

⇒ It's the same.

☆☆☆ For any "n" that is a boundary point between two regions... where the product graph has something in both regions...

→ In other words, for any "n" that is the boundary point between two regions where the product graph is not all zeros,

⇒ The formulas for these two regions will always agree at the boundary point.

⇒ The "n" that is at the boundary can always be considered to be:

- The last "n" in the "left" case,
- Or the first "n" in the "right" case.



- How we choose this determines which case gets the "=" in the inequalities.

- If we do it the way we did on pages 3.45 and 3.46 when we first worked this problem,

- which is the same as how we did it on pages 3.62 and 3.63 when we further analyzed the cases for this problem,

- Then we put $n=4$ as the first "n" in case III, and we get:

$$\text{case II) } 0 \leq n < 4$$

$$\text{case III) } 4 \leq n < 6$$

→ $n=4$ is the first "n" in case III.

- If we instead put $n=4$ as the last "n" in case II, then we get:

$$\text{Case II) } 0 \leq n \leq 4$$

$$\text{Case III) } 4 < n < 6$$

↖ now the "=" is here
↑ no "=" here

→ Either way is actually correct.

- What is important :

☆☆ However you decide to do it, you must make sure that every "n" is included in one of your cases!!!

⇒ This would be incorrect :

case II) $0 \leq n < 4$ X

case III) $4 < n < 6$ X

⇒ Incorrect because $n=4$ is not included in either case...
 $n=4$ is left out XXX

- You must make sure that your cases include all the n's.

- As a matter of convention, I usually pick my boundary points so that the cases

look like

$$a \leq n < b$$

↑
equal "="
going here

↑
not here

} as we did in all of the examples on pages 3.40 - 3.50.

- This makes the solution look a little bit more "elegant."

- From what we have said about how to find the regions on pages 3.51-3.71, you might be starting to think that maybe the first region, or first case, which always starts at $n = -\infty$,
 - Also always has $y[n] = 0$. XX
 - \Rightarrow But that's wrong!!!

\rightarrow If either $x[n]$ is a left-sided signal or $h[n]$ is a left-sided signal,

\Rightarrow Then the first case (which includes $n = -\infty$) will not have $y[n] = 0$!!

\Rightarrow This is illustrated by the example we did back on page 3.48... where we got

$$y[n] = \begin{cases} 2^{n+1}, & n < 0 \\ 2, & n \geq 0 \end{cases}$$

\Rightarrow The first case does not always have $y[n] = 0$!!!

WHAT TO DO IF ONE OF THE SIGNALS IS

DEFINED "PIECEWISE"

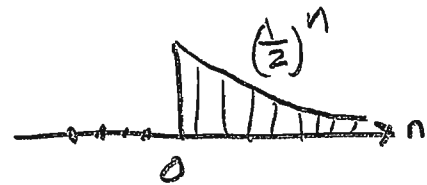
- Sometimes, especially in ECE 3793, you may get a convolution problem

$$x[n] \rightarrow \boxed{H} \rightarrow y[n] = x[n] * h[n]$$

\Rightarrow Where one of the signals $x[n]$ or $h[n]$ has "two parts" and is defined "piecewise".

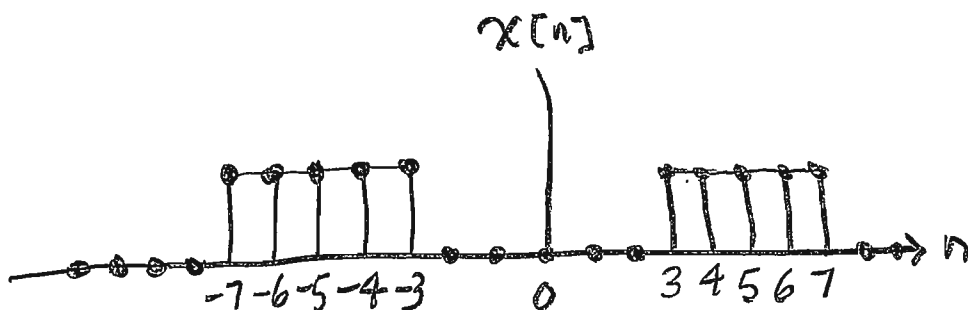
- For example, you might get

$$h[n] = \left(\frac{1}{2}\right)^n u[n]$$



and

$$x[n] = \begin{cases} 1, & -7 \leq n \leq -3 \\ 1, & 3 \leq n \leq 7 \\ 0, & \text{otherwise} \end{cases} = (u[n+7] - u[n+2]) + (u[n-3] - u[n-8])$$



- You can handle these problems by using the distributive property to break the problem into two simpler convolutions... i.e.,

$$\begin{aligned}
 & \left(\begin{array}{c} \text{[Diagram: Two rectangular pulses on a horizontal axis labeled } n. \text{ The first pulse is shaded with diagonal lines. The second pulse is unshaded.]} \\ \rightarrow n \end{array} \right) * \left(\begin{array}{c} \text{[Diagram: A triangular pulse on a horizontal axis labeled } n. \text{ The peak is at } n=0. \text{ The pulse is shaded with diagonal lines.]} \\ \rightarrow n \end{array} \right) \\
 &= \left(\begin{array}{c} \text{[Diagram: A single rectangular pulse on a horizontal axis labeled } n. \text{ The pulse is shaded with diagonal lines.]} \\ \rightarrow n \end{array} * \begin{array}{c} \text{[Diagram: A triangular pulse on a horizontal axis labeled } n. \text{ The peak is at } n=0. \text{ The pulse is shaded with diagonal lines.]} \\ \rightarrow n \end{array} \right) \\
 &+ \left(\begin{array}{c} \text{[Diagram: A single rectangular pulse on a horizontal axis labeled } n. \text{ The pulse is unshaded.]} \\ \rightarrow n \end{array} * \begin{array}{c} \text{[Diagram: A triangular pulse on a horizontal axis labeled } n. \text{ The peak is at } n=0. \text{ The pulse is shaded with diagonal lines.]} \\ \rightarrow n \end{array} \right)
 \end{aligned}$$

- For the "example" problem on page 3.73, this would give you:

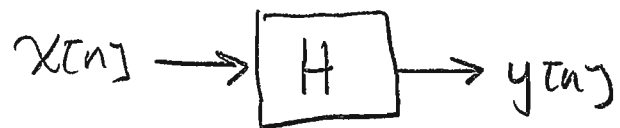
$$\begin{aligned}
 y[n] &= x[n] * h[n] \\
 &= \left\{ (u[n+7] - u[n+2]) + (u[n-3] - u[n-8]) \right\} * \left(\frac{1}{2}\right)^n u[n] \\
 &= (u[n+7] - u[n+2]) * \left(\frac{1}{2}\right)^n u[n] + (u[n-3] - u[n-8]) * \left(\frac{1}{2}\right)^n u[n]
 \end{aligned}$$



work each part using the techniques we have learned in this module.

MODULE 3 SUMMARY

- We learned that the output of an LTI system is given by the convolution of the input with the impulse response:



$$\begin{aligned} y[n] &= x[n] * h[n] \\ &= \sum_{k=-\infty}^{\infty} x[k] h[n-k] \\ &= \sum_{k=-\infty}^{\infty} h[k] x[n-k] \end{aligned}$$

- We learned that when $x[n]$ and $h[n]$ can both be written as short sums of the shifts of $\delta[n]$, then we can find $y[n]$ using the simpler "convolution with deltas" method.
- We learned the more general "graphical convolution" method that can always be used to find $y[n]$.