

ECE 3793

Test 1

Thursday, October 14, 1999

12:00 PM - 1:15 PM

Fall 1999

Dr. Havlicek

Name: SOLUTION

Student Num: _____

Directions: There are **five** problems on this test. Work any **four** of them. Only **four** problems will be graded. You have 75 minutes to complete the test. All work must be your own. You may use one 8.5 × 11 inch two-sided note sheet as well as the summation formula sheet handed out in class.

SHOW ALL OF YOUR WORK for maximum partial credit!

GOOD LUCK!

Circle the numbers of the four problems you wish to have graded:

1. 2. 3. 4. 5.

SCORE:

1. (25) _____

2. (25) _____

3. (25) _____

4. (25) _____

5. (25) _____

TOTAL (100):

1. 25 pts. The input $x(t)$ and output $y(t)$ of a system are related by

$$y(t) = \begin{cases} 0, & t < 0, \\ x(t) + x(t-2), & t \geq 0. \end{cases}$$

(a) 5 pts. Is the system memoryless? Justify your answer.

The system is not memoryless, because $y(t)$ depends on the past input $x(t-2)$ when $t \geq 0$.

(b) 5 pts. Is the system causal? Justify your answer.

The output $y(t)$ never depends on future values of the input.

Therefore, the system is causal.

(c) 5 pts. Is the system stable? Justify your answer.

Suppose $x(t)$ is a bounded input. Then $\exists B \in \mathbb{R}, B > 0$, such that $|x(t)| \leq B \forall t$.

$$\begin{aligned} \text{Then } |y(t)| &\leq |x(t) + x(t-2)| \\ &\leq |x(t)| + |x(t-2)| \\ &\leq B + B \\ &= 2B \\ &< \infty. \end{aligned} \quad \Rightarrow \text{The system is stable.}$$

Problem 1, cont...

(d) 5 pts. Is the system linear? Justify your answer.

$$\text{Let } y_1(t) = \begin{cases} 0, & t < 0 \\ x_1(t) + x_1(t-2), & t \geq 0 \end{cases}. \quad \text{Let } y_2(t) = \begin{cases} 0, & t < 0 \\ x_2(t) + x_2(t-2), & t \geq 0 \end{cases}.$$

$$\text{Let } x_3(t) = ax_1(t) + bx_2(t), \quad a, b \in \mathbb{R}.$$

$$\text{Then } y_3(t) = \begin{cases} 0, & t < 0 \\ x_3(t) + x_3(t-2), & t \geq 0 \end{cases} = \begin{cases} 0+0, & t < 0 \\ ax_1(t) + bx_2(t) + ax_1(t-2) + bx_2(t-2), & t \geq 0 \end{cases}.$$

$$= \begin{cases} 0+0, & t < 0 \\ a[x_1(t) + x_1(t-2)] + b[x_2(t) + x_2(t-2)], & t \geq 0 \end{cases}$$

$$= ay_1(t) + by_2(t) \quad \checkmark$$

The system is linear.

(e) 5 pts. Is the system time invariant? Justify your answer.

$$\text{Let } x_1(t) = 1 \quad \forall t. \quad \text{Then } x_1(t) + x_1(t-2) = 1+1 = 2.$$

$$\text{So } y_1(t) = \begin{cases} 0, & t < 0 \\ 2, & t \geq 0 \end{cases} = 2u(t).$$

$$\text{Now let } x_2(t) = x_1(t-t_0) = 1 = x_1(t).$$

$$\text{NOTE: } y_1(t-t_0) = 2u(t-t_0).$$

$$\text{But, } y_2(t) = \begin{cases} 0, & t < 0 \\ 2, & t \geq 0 \end{cases} = 2u(t) \neq y_1(t-t_0).$$

Therefore, the system is not time invariant.

2. 25 pts. An invertible discrete-time LTI system H has unit pulse response

$$h[n] = u[n].$$

Find the unit pulse response $g[n]$ of the inverse system G .

For H , the output is

$$\begin{aligned} y[n] &= x[n] * h[n] \\ &= \sum_{k=-\infty}^{\infty} x[k] u[n-k] \\ &= \sum_{k=-\infty}^n x[k] \end{aligned}$$

$$\text{So } y[n-1] = \sum_{k=-\infty}^{n-1} x[k]$$

$$\text{So } y[n] - y[n-1] = \sum_{k=-\infty}^n x[k] - \sum_{k=-\infty}^{n-1} x[k] = x[n].$$

$$\text{Then } x[n] = y[n] - y[n-1].$$

Then the input/output relation for the inverse system G is

$$y[n] = x[n] - x[n-1].$$

In other words, for the system G ,

$$\begin{aligned} y[n] &= x[n] * \delta[n] - x[n] * \delta[n-1] \\ &= x[n] * \{ \delta[n] - \delta[n-1] \}. \end{aligned}$$

Therefore, the unit pulse response of G is

$$\underline{\underline{g[n] = \delta[n] - \delta[n-1]}}$$

3. 25 pts. The unit pulse response of a discrete-time LTI system is given by

$$h[n] = u[n].$$

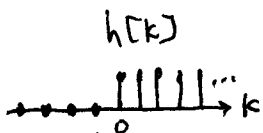
(a) 5 pts. Is the system stable? Justify your answer.

$$\sum_{n=-\infty}^{\infty} |h[n]| = \sum_{n=0}^{\infty} 1 \rightarrow \infty.$$

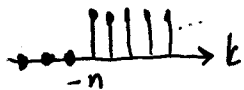
Therefore, the system is not stable.

(b) 20 pts. Find the system output when the input is

$$x[n] = 2^n \{u[n] - u[n-7]\} = \begin{cases} 2^n, & 0 \leq n \leq 6 \\ 0, & \text{otherwise.} \end{cases}$$



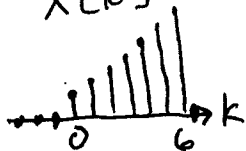
$h[k+n]$



$h[n-k]$



$x[k]$



case I: $n < 0$; $y[n] = 0$

case II: $0 \leq n < 6$:

$$y[n] = \sum_{k=0}^n x[k] h[n-k]$$

$$= \sum_{k=0}^n 2^k \cdot 1$$

$$= \frac{2^0 - 2^{n+1}}{1-2} = -(1-2^{n+1}) = 2^{n+1} - 1.$$

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More Workspace for Problem 3...

case III: $6 \leq n$:

$$y[n] = \sum_{k=0}^6 x[k] h[n-k]$$

$$= \sum_{k=0}^6 2^k \cdot 1$$

$$= \frac{2^0 - 2^7}{1-2} = -(1-2^7) = 2^7 - 1 = 128 - 1 = 127.$$

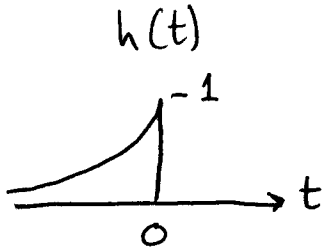
All together:

$$y[n] = \begin{cases} 0, & n < 0 \\ 2^{n+1} - 1, & 0 \leq n < 6 \\ 127, & 6 \leq n \end{cases} = (2^{n+1} - 1) (u[n] - u[n-7])$$

4. 25 pts. The impulse response of a continuous-time LTI system is given by

$$h(t) = e^{2t}u(-t).$$

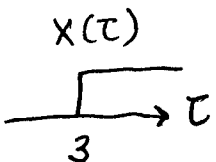
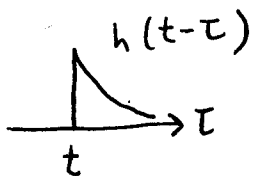
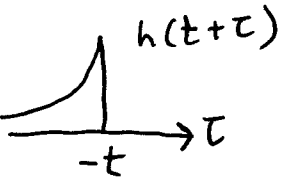
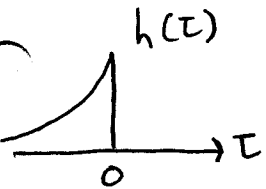
(a) 5 pts. Is the system causal? Justify your answer.



The system is not causal because $h(-1) = e^{-2} \neq 0$.

(b) 20 pts. Find the system output when the input is

$$x(t) = u(t-3).$$



Case I: $t \leq 3$:

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_3^{\infty} 1 \cdot e^{2(t-\tau)} d\tau$$

$$= e^{2t} \int_3^{\infty} e^{-2\tau} d\tau$$

$$= e^{2t} \left(-\frac{1}{2}\right) \left[e^{-2\tau} \right]_3^{\infty}$$

$$= -\frac{e^{2t}}{2} \lim_{A \rightarrow \infty} \left[e^{-2A} - e^{-6} \right]$$

$$= \frac{e^{2t}}{2} e^{-(2 \cdot 3)} = \frac{1}{2} e^{+2(t-3)}$$



More Workspace for Problem 4...

case II: $t > 3$:

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_t^{\infty} 1 \cdot e^{2(t-\tau)} d\tau$$

$$= e^{2t} \int_t^{\infty} e^{-2\tau} d\tau$$

$$= -\frac{e^{2t}}{2} \left[e^{-2\tau} \right]_t^{\infty}$$

$$= -\frac{e^{2t}}{2} \lim_{A \rightarrow \infty} \left[e^{-2A} - e^{-2t} \right]$$

$$= +\frac{e^{2t}}{2} e^{-2t} = \frac{1}{2}$$

All Together:

$$y(t) = \begin{cases} \frac{1}{2} e^{2(t-3)}, & t \leq 3 \\ \frac{1}{2}, & t > 3 \end{cases}$$

5. 25 pts. A discrete-time system H is formed by the parallel connection of two discrete-time LTI systems H_1 and H_2 . The unit pulse response $h_1[n]$ of H_1 is given by

$$h_1[n] = u[n] - u[n - 47].$$

The unit pulse response $h_2[n]$ of H_2 is given by

$$h_2[n] = -u[n - 1] + u[n - 47].$$

Find the output $y[n]$ of the system H when the input is

$$x[n] = \sum_{m=-\infty}^{\infty} \{\delta[n - 4m] - \delta[n - 1 - 4m]\}.$$

Since H_1 and H_2 are LSI, so is H .

The impulse response of H is (for a parallel connection)

$$\begin{aligned} h[n] &= h_1[n] + h_2[n] \\ &= u[n] - u[n - 47] - u[n - 1] + u[n - 47] \\ &= u[n] - u[n - 1] \\ &= \delta[n]. \end{aligned}$$

$$\begin{aligned} y[n] &= x[n] * \delta[n] \\ &= x[n] \\ &= \sum_{m=-\infty}^{\infty} \{\delta[n - 4m] - \delta[n - 1 - 4m]\} \end{aligned}$$