

ECE 3793

Test 1

Tuesday, March 13, 2001

7:00 PM - 10:00 PM

Spring 2001

Dr. Havlicek

Name: SOLUTION

Student Num: _____

Directions: This test is closed book and closed notes. You have 180 minutes to complete the test. All work must be your own. There are **five** problems. Work any **four** of them. Only **four** problems will be graded. Below, you must circle the numbers of the **four** problems you wish to have graded. Formulas appear at the **end** of the test.

SHOW ALL OF YOUR WORK for maximum partial credit!

GOOD LUCK!

Circle the numbers of the **four** problems you wish to have graded:

1. 2. 3. 4. 5.

SCORE:

1. (25) _____

2. (25) _____

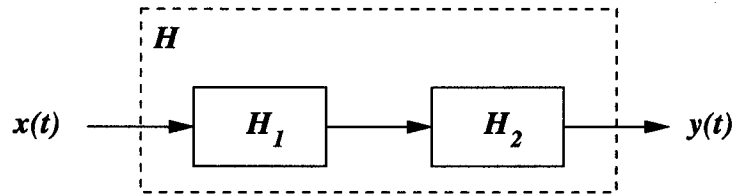
3. (25) _____

4. (25) _____

5. (25) _____

TOTAL (100):

1. **25 pts.** Consider a continuous-time system H formed by connecting two systems H_1 and H_2 in series as shown in the figure below. System H has input $x(t)$ and output $y(t)$.



The input/output relation for system H_1 is $y(t) = tx(t+2) + 5$. The output of H_1 is fed directly into system H_2 . System H_2 is an ideal differentiator with input/output relation $y(t) = \frac{d}{dt}x(t)$.

Hint: In calculating the input/output relation for the overall system H , be sure to apply the chain rule carefully when you differentiate the output of system H_1 .

- (a) **5 pts.** Is the system H memoryless? Justify your answer.

The I/O relation for H is

$$y(t) = \frac{d}{dt} \{ tx(t+2) + 5 \} = t \frac{d}{dt} x(t+2) + x(t+2)$$

\Rightarrow since $y(t)$ depends on the future input $x(t+2)$, the system is not memoryless

- (b) **5 pts.** Is the system H causal? Justify your answer.

H is not causal for the same reason as in part (a):

$y(t)$ depends on the future input $x(t+2)$.

Problem 1, cont...

(c) 5 pts. Is the system H BIBO stable? Justify your answer.

Let the input be $x(t) = u(t)$. Then $|x(t)| \leq 1$, so $x(t)$ is a bounded input signal.

The output in this case is

$$\begin{aligned} y(t) &= t \frac{d}{dt} u(t+2) + u(t+2) \\ &= t \delta(t+2) + u(t+2) = u(t+2) - 2\delta(t+2) \end{aligned}$$

Since $y(-2) \rightarrow -\infty$, the output is not bounded.

Since a bounded input produced an unbounded output, the system is not stable.

(d) 5 pts. Is the system H linear? Justify your answer.

Let $y_1(t)$ be the output when $x_1(t)$ is the input:

$$y_1(t) = H\{x_1(t)\} = t \frac{d}{dt} x_1(t+2) + x_1(t+2).$$

Let $y_2(t)$ be the output when $x_2(t)$ is the input:

$$y_2(t) = H\{x_2(t)\} = t \frac{d}{dt} x_2(t+2) + x_2(t+2).$$

Let $x_3(t) = ax_1(t) + bx_2(t)$ where a & b are constants.

$$\text{Then } y_3(t) = t \frac{d}{dt} x_3(t+2) + x_3(t+2)$$

$$= t \frac{d}{dt} \{ax_1(t+2) + bx_2(t+2)\} + ax_1(t+2) + bx_2(t+2)$$

$$= at \frac{d}{dt} x_1(t+2) + bt \frac{d}{dt} x_2(t+2) + ax_1(t+2) + bx_2(t+2)$$

$$= a \left\{ t \frac{d}{dt} x_1(t+2) + x_1(t+2) \right\} + b \left\{ t \frac{d}{dt} x_2(t+2) + x_2(t+2) \right\}$$

$$= ay_1(t) + by_2(t) \quad \checkmark \quad \text{The system is } \underline{\text{linear}}.$$

Problem 1, cont...

(e) 5 pts. Is the system H time invariant? Justify your answer.

I think that H is not time invariant because of the "t" out front in the term $t \frac{d}{dt} x(t+z)$.

Proof: Let $x_1(t) = u(t)$.

$$\begin{aligned} \text{Then } y_1(t) &= t \frac{d}{dt} u(t+z) + u(t+z) \\ &= t \delta(t+z) + u(t+z) \\ &= u(t+z) - 2\delta(t+z). \end{aligned}$$

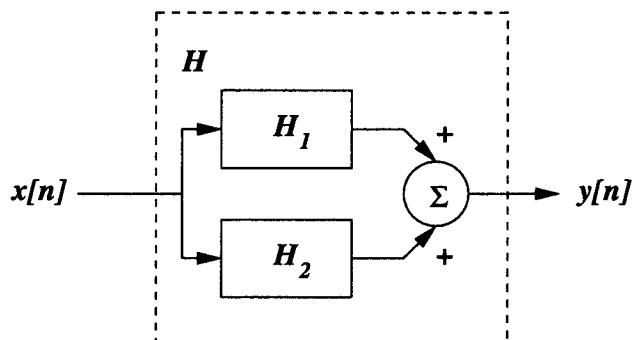
$$\begin{aligned} \text{Let } t_0 = 3. \text{ Then } y_1(t-t_0) &= y_1(t-3) = u(t-3+z) - 2\delta(t-3+z) \\ &= u(t-1) - 2\delta(t-1). \end{aligned}$$

Now let $x_2(t) = x_1(t-t_0) = u(t-3)$.

$$\begin{aligned} \text{Then } y_2(t) &= t \frac{d}{dt} x_2(t+z) + x_2(t+z) \\ &= t \frac{d}{dt} u(t-1) + u(t-1) \\ &= t \delta(t-1) + u(t-1) \\ &= u(t-1) + \delta(t-1) \neq y_1(t-t_0). \end{aligned}$$

Since $y_2(t) \neq y_1(t-t_0)$, the system is not time invariant.

2. 25 pts. The discrete-time system H shown in the figure below is formed by connecting two LTI systems H_1 and H_2 in parallel.



The impulse response of LTI system H_1 is given by

$$h_1[n] = \left(-\frac{1}{2}\right)^n u[n-2]$$

and the impulse response of LTI system H_2 is given by

$$h_2[n] = (1.01)^n u[1-n].$$

- (a) 10 pts. Is H an LTI system? If you say **yes**, then state the reason and find the impulse response $h[n]$. If instead you say **no**, then prove that it is not.

H is an LTI system, because, as we proved in class, the parallel connection of any two LTI systems is itself another LTI system.

The impulse response of H is given by

$$\begin{aligned} h[n] &= h_1[n] + h_2[n] \\ &= (1.01)^n u[1-n] + \left(-\frac{1}{2}\right)^n u[n-2] \end{aligned}$$

Problem 2, cont...

(b) 5 pts. Is the system H memoryless? Justify your answer.

A discrete-time LTI system H is memoryless iff the impulse response is a constant times $\delta[n]$.

In this case, $h[n]$ is nonzero $\forall n \in \mathbb{Z}$, so the system is not memoryless.

(c) 5 pts. Is the system H causal? Justify your answer.

A discrete-time LTI system is causal iff the impulse response is zero $\forall n < 0$. In this case,

$$h[-1] = (1.01)^{-1} = \frac{1}{1.01} \neq 0.$$

So the system is not causal.

(d) 5 pts. Is the system H BIBO stable? Justify your answer.

A discrete-time LTI system is stable iff the impulse response is absolutely summable. We have

$$\sum_{n=-\infty}^{\infty} |h[n]| = \sum_{n=-\infty}^1 (1.01)^n + \sum_{n=2}^{\infty} |(-\frac{1}{2})^n|$$

$$= \sum_{n=-\infty}^0 (1.01)^n + (1.01)^1 + \sum_{n=2}^{\infty} (\frac{1}{2})^n$$

$$= 1.01 + \sum_{n=0}^{\infty} \frac{1}{1.01} + \sum_{n=0}^{\infty} (\frac{1}{2})^n - 1 - \frac{1}{2}$$

$$= \frac{1}{1 - \frac{1}{1.01}} + \frac{1}{1 - \frac{1}{2}} - 0.49 = 101 + 2 - 0.49$$

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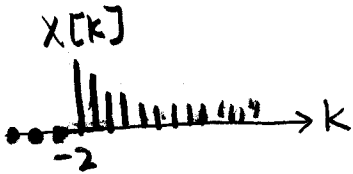
$$= \underline{\underline{102.51}} < \infty$$

The system is stable.

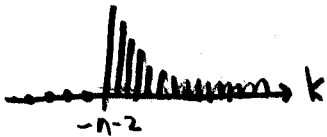
3. 25 pts. Consider a discrete-time LTI system H with impulse response

$$h[n] = \left(\frac{1}{4}\right)^{-n} u[-n+2].$$

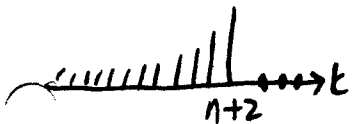
The system input is given by $x[n] = \left(\frac{1}{2}\right)^n u[n+2]$. Find the system output $y[n]$.



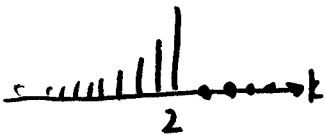
$x[n+k]$



$x[n-k]$



$h[k]$



$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$

I) $n+2 < 2 \Rightarrow n < 0$:

$$\begin{aligned} y[n] &= \sum_{k=-\infty}^{n+2} \left(\frac{1}{4}\right)^{-k} \left(\frac{1}{2}\right)^{n-k} = \left(\frac{1}{2}\right)^n \sum_{k=-\infty}^{n+2} \left(\frac{1}{4}\right)^{-k} \left(\frac{1}{2}\right)^{-k} \\ &= \left(\frac{1}{2}\right)^n \sum_{k=-\infty}^{n+2} \left(\frac{1}{8}\right)^{-k} = \left(\frac{1}{2}\right)^n \sum_{k=-\infty}^{n+2} 8^k \\ &= \left(\frac{1}{2}\right)^n \lim_{A \rightarrow \infty} \frac{8^{-A} - 8^{n+3}}{1-8} = \left(\frac{1}{2}\right)^n \frac{0 - 8^{n+3}}{-7} \\ &= \left(\frac{1}{2}\right)^n 8^n \frac{8^3}{7} = \frac{8^3}{7} \left(\frac{1}{2} \cdot 8\right)^n = \frac{8^3}{7} 4^n. \end{aligned}$$

II) $n+2 \geq 2 \Rightarrow n \geq 0$:

$$\begin{aligned} y[n] &= \sum_{k=-\infty}^2 \left(\frac{1}{4}\right)^{-k} \left(\frac{1}{2}\right)^{n-k} = \left(\frac{1}{2}\right)^n \sum_{k=-\infty}^2 \left(\frac{1}{4}\right)^{-k} \left(\frac{1}{2}\right)^{-k} \\ &= \left(\frac{1}{2}\right)^n \sum_{k=-\infty}^2 \left(\frac{1}{8}\right)^{-k} = \left(\frac{1}{2}\right)^n \sum_{k=-\infty}^2 8^k \\ &= \left(\frac{1}{2}\right)^n \lim_{A \rightarrow \infty} \frac{8^{-A} - 8^3}{1-8} = \left(\frac{1}{2}\right)^n \frac{0 - 8^3}{-7} = \frac{8^3}{7} \left(\frac{1}{2}\right)^n. \end{aligned}$$

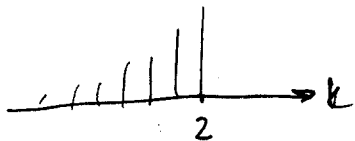
All Together

$$y[n] = \begin{cases} \frac{8^3}{7} 4^n, & n < 0 \\ \frac{8^3}{7} \left(\frac{1}{2}\right)^n, & n \geq 0 \end{cases}$$

③ The other way:

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

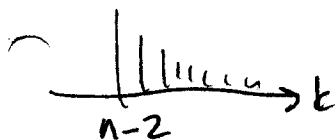
$h[k]$



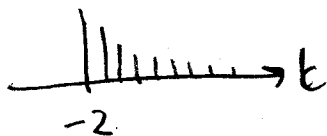
$h[n+k]$



$h[n-k]$



$x[k]$



I) $n-2 < -2 \Rightarrow n < 0$:

$$\begin{aligned} y[n] &= \sum_{k=-2}^{\infty} \left(\frac{1}{2}\right)^k \left(\frac{1}{4}\right)^{k-n} = 4^n \sum_{k=-2}^{\infty} \left(\frac{1}{8}\right)^k \\ &= 4^n \frac{\left(\frac{1}{8}\right)^{-2} - \left(\frac{1}{8}\right)^{\infty}}{1 - \frac{1}{8}} \\ &= 4^n \left(\frac{8}{7}\right) 8^2 = \frac{8^3}{7} 4^n \end{aligned}$$

II) $n-2 \geq -2 \Rightarrow n \geq 0$:

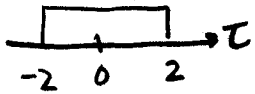
$$\begin{aligned} y[n] &= \sum_{k=n-2}^{\infty} \left(\frac{1}{2}\right)^k \left(\frac{1}{4}\right)^{k-n} = 4^n \sum_{k=n-2}^{\infty} \left(\frac{1}{8}\right)^k \\ &= 4^n \frac{\left(\frac{1}{8}\right)^{n-2} - \left(\frac{1}{8}\right)^{\infty}}{1 - \frac{1}{8}} = 4^n \left(\frac{8}{7}\right) 8^{2-n} \\ &= \frac{8^3}{7} 4^n \left(\frac{1}{8}\right)^n = \frac{8^3}{7} \left(\frac{1}{2}\right)^n \end{aligned}$$

All Together:

$$y[n] = \begin{cases} \frac{8^3}{7} 4^n, & n < 0 \\ \frac{8^3}{7} \left(\frac{1}{2}\right)^n, & n \geq 0. \end{cases}$$

4. 25 pts. Consider a continuous-time LTI system H with impulse response $h(t) = u(t+2) - u(t-2)$. The system input is given by $x(t) = e^{j\pi t}u(t)$. Find the system output $y(t)$.

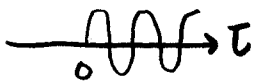
$h(\tau)$



$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau$$

I) $t < -2$: $y(t) = 0$.

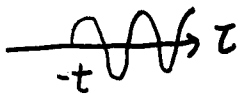
$x(\tau)$



II) $-2 \leq t < 2$:

$$y(t) = \int_{-2}^t e^{j\pi(t-\tau)} d\tau = e^{j\pi t} \int_{-2}^t e^{-j\pi\tau} d\tau$$

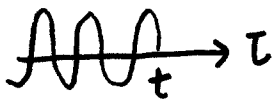
$x(t+\tau)$



$$= \frac{e^{j\pi t}}{-j\pi} \left[e^{-j\pi\tau} \right]_{\tau=-2}^t$$

$$= \frac{e^{j\pi t}}{-j\pi} \left[e^{-j\pi t} - e^{j2\pi} \right] = \frac{1 - \overbrace{e^{j2\pi}}^1 e^{j\pi t}}{-j\pi}$$

$x(t-\tau)$



$$= \frac{e^{j\pi t} - 1}{j\pi}$$

III) $t \geq 2$:

$$y(t) = \int_{-2}^2 e^{j\pi(t-\tau)} d\tau = e^{j\pi t} \int_{-2}^2 e^{-j\pi\tau} d\tau$$

$$= \frac{e^{j\pi t}}{-j\pi} \left[e^{-j\pi\tau} \right]_{\tau=-2}^2$$

$$= \frac{e^{j\pi t}}{-j\pi} \left[e^{-j2\pi} - e^{j2\pi} \right]$$

$$= \frac{e^{j\pi t}}{-j\pi} [1 - 1] = 0$$

Together

$$y(t) = \begin{cases} 0, & t < -2 \\ \frac{e^{j\pi t} - 1}{j\pi}, & -2 \leq t < 2 \\ 0, & t \geq 2 \end{cases} = \frac{e^{j\pi t}}{j\pi} [u(t+2) - u(t-2)]$$

5. 25 pts. Determine if the discrete-time signal

$$x[n] = \cos \left[\frac{\pi}{8} n^2 \right]$$

is periodic. If the signal is periodic, then find the fundamental period.

If $x[n]$ is periodic with period N , then

$$x[n] = x[n+N] \quad \forall n \in \mathbb{Z}$$

$$\text{Then } \cos \left[\frac{\pi}{8} n^2 \right] = \cos \left[\frac{\pi}{8} (n+N)^2 \right] \quad \forall n \in \mathbb{Z}.$$

Then $\frac{\pi}{8} n^2$ and $\frac{\pi}{8} (n+N)^2$ differ by an integer multiple of $2\pi \quad \forall n \in \mathbb{Z}$.

Then for some integer k , $\frac{\pi}{8} (n+N)^2 - \frac{\pi}{8} n^2 = k2\pi \quad \forall n \in \mathbb{Z}$

$$\frac{\pi}{8} (n^2 + 2nN + N^2) - \frac{\pi}{8} n^2 = k2\pi \quad \forall n \in \mathbb{Z}$$

$$\frac{\pi}{8} n^2 + \frac{2\pi}{8} nN + \frac{\pi}{8} N^2 - \frac{\pi}{8} n^2 = k2\pi \quad \forall n \in \mathbb{Z}$$

$$\frac{2\pi}{8} nN + \frac{\pi}{8} N^2 = k2\pi \quad \forall n \in \mathbb{Z}$$

$$\frac{2n}{8} N + \frac{1}{8} N^2 = 2k \quad (\text{integer}) \quad \forall n \in \mathbb{Z}$$

$$n \frac{N}{8} + \frac{N^2}{16} = \text{integer} \quad \forall n \in \mathbb{Z}.$$

$\Rightarrow N$ is the smallest positive integer that is divisible by 8 such that N^2 is divisible by 16.

$$\text{Let } N = 8m, \quad m \in \mathbb{Z}.$$

Then $N^2 = 64m^2$ must be divisible by 8.

Since $64m^2$ is divisible⁹ by 8 for any integer m ,

choose $m=1$ to get the smallest satisfactory N .

$$\Rightarrow N = 8 \cdot m = 8 \cdot 1 = \underline{\underline{8}} \rightarrow$$

More Workspace for Problem 5...

$x[n]$ is periodic with fundamental
period $N=8$.