

# ECE 3793

## Test 2

Thursday, April 25, 2002  
7:00 PM - 10:00 PM

Spring 2002

Dr. Havlicek

Name: SOLUTION

Student Num: \_\_\_\_\_

**Directions:** This test is closed book and closed notes. You have 180 minutes to complete the test. All work must be your own. There are **four** problems. Work all **four**.

► Formulas appear **after** problem four.

SHOW ALL OF YOUR WORK for maximum partial credit!

### GOOD LUCK!

SCORE:

1. (25) \_\_\_\_\_

2. (25) \_\_\_\_\_

3. (25) \_\_\_\_\_

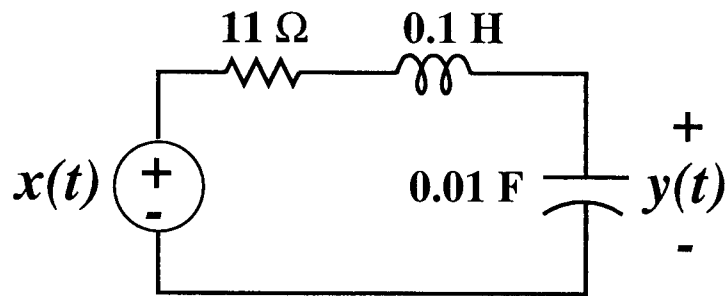
4. (25) \_\_\_\_\_

\_\_\_\_\_

TOTAL (100):

\_\_\_\_\_

1. 25 pts. Consider the causal, stable LTI system  $H$  shown below. Voltage  $x(t)$  is the system input and voltage  $y(t)$  is the system output.



- (a) 15 pts. Find the system frequency response  $H(\omega)$ .

RESISTOR:  $V_R(t) = 11i(t)$ ; INDUCTOR:  $V_L(t) = 0.1i'(t)$

CAPACITOR:  $i(t) = 0.01y'(t)$ .

$$\rightarrow i'(t) = 0.01y''(t) \rightarrow V_L(t) = (0.1)(0.01)y''(t) = (0.001)y''(t).$$

$$\begin{aligned} \text{KVL: } x(t) &= V_R(t) + V_L(t) + y(t) \\ &= (11)(0.01)y'(t) + (0.001)y''(t) + y(t) \\ &= (0.11)y'(t) + (0.001)y''(t) + y(t) \end{aligned}$$

$$1000x(t) = y''(t) + 110y'(t) + 1000y(t)$$

$$1000X(\omega) = (j\omega)^2 Y(\omega) + 110(j\omega)Y(\omega) + 1000Y(\omega)$$

$$1000X(\omega) = [(j\omega)^2 + 110j\omega + 1000] Y(\omega)$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{1000}{(j\omega)^2 + 110j\omega + 1000}$$

Problem 1, cont...

$$H(\omega) = \frac{1000}{(j\omega)^2 + 110j\omega + 1000} = \frac{1000}{(j\omega + 10)(j\omega + 100)}$$
$$= \frac{A}{j\omega + 10} + \frac{B}{j\omega + 100}$$

$$A = \frac{1000}{\theta + 100} \Big|_{\theta = -10} = \frac{1000}{90} = \frac{100}{9}$$

$$B = \frac{1000}{\theta + 10} \Big|_{\theta = -100} = \frac{1000}{-90} = -\frac{100}{9}$$

(b) 10 pts. Find the system impulse response  $h(t)$ .

$$H(\omega) = \frac{100}{9} \frac{1}{j\omega + 10} - \frac{100}{9} \frac{1}{j\omega + 100}$$

$$= \frac{100}{9} \left[ \frac{1}{j\omega + 10} - \frac{1}{j\omega + 100} \right]$$

$$h(t) = \frac{100}{9} \left[ e^{-10t} - e^{-100t} \right] u(t)$$

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2. 25 pts. Consider an LTI system  $G$  with input  $x(t)$  and output  $y(t)$  related by

$$y''(t) + 3y'(t) + 2y(t) = x''(t) + 6x'(t) + 9x(t).$$

(a) 8 pts. Find the system frequency response  $G(\omega)$ .

$$[(j\omega)^2 + 3j\omega + 2] Y(\omega) = [(j\omega)^2 + 6j\omega + 9] X(\omega)$$

$$G(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{(j\omega)^2 + 6j\omega + 9}{(j\omega)^2 + 3j\omega + 2}$$

(b) 5 pts. Let  $H$  be the *inverse system* of  $G$ . Then  $H$  is also an LTI system. Find the frequency response  $H(\omega)$  of the inverse system.

$$H(\omega) = \frac{1}{G(\omega)} = \frac{(j\omega)^2 + 3j\omega + 2}{(j\omega)^2 + 6j\omega + 9}$$



Problem 2, cont...

(c) 12 pts. Find the impulse response  $h(t)$  of the inverse system.

$H(\omega)$  is not a proper fraction, so we must do long division

$$\left. \begin{array}{l} 1 \\ (j\omega)^2 + 6j\omega + 9 \end{array} \right\} \left. \begin{array}{l} (j\omega)^2 + 3j\omega + 2 \\ (j\omega)^2 + 6j\omega + 9 \\ \hline -3j\omega - 7 \end{array} \right\} H(\omega) = 1 - \frac{3j\omega + 7}{(j\omega)^2 + 6j\omega + 9}$$

$$\frac{3j\omega + 7}{(j\omega)^2 + 6j\omega + 9} = \frac{3j\omega + 7}{(j\omega + 3)^2} = \frac{A}{j\omega + 3} + \frac{B}{(j\omega + 3)^2}$$

$$B = 3\theta + 7 \Big|_{\theta = \theta - 3} = -9 + 7 = \underline{-2}$$

$$\frac{d}{d\theta} (\theta + 3)A \Big|_{\theta = -3} + \frac{d}{d\theta} B \Big|_{\theta = -3} = \frac{d}{d\theta} (3\theta + 7) \Big|_{\theta = -3}$$

$$\underline{A = 3}$$

$$\frac{3j\omega + 7}{(j\omega)^2 + 6j\omega + 9} = \frac{3}{j\omega + 3} - \frac{2}{(j\omega + 3)^2}$$

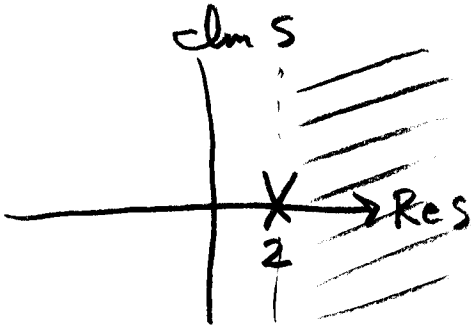
$$H(\omega) = 1 + \frac{2}{(j\omega + 3)^2} - \frac{3}{j\omega + 3}$$

$$\underline{\underline{h(t) = \delta(t) + 2te^{-3t}u(t) - 3e^{-3t}u(t)}}$$

3. 25 pts. A causal LTI system  $F$  has transfer function

$$F(s) = \frac{1}{s-2}.$$

(a) 3 pts. Give a pole zero plot for  $F(s)$ . What is the ROC of  $F(s)$ ? Justify your answer.



Since  $F$  is causal, ROC is the right half-plane to the right of the rightmost pole.

$$\text{ROC: } \text{Re}[s] > 2.$$

(b) 2 pts. Is the system  $F$  BIBO stable? Justify your answer.

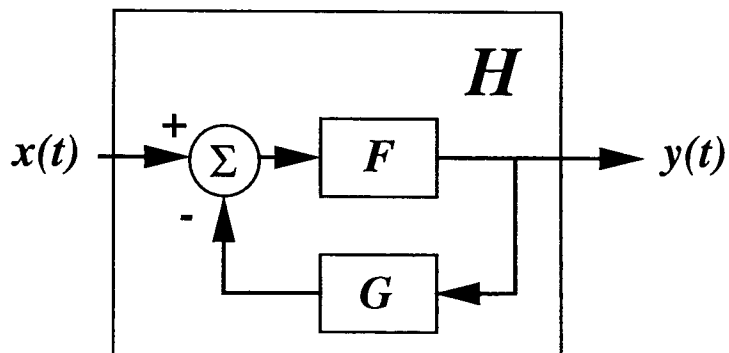
NOT STABLE because the pole at  $s=2$  is in the RHP.

(c) 2 pts. Consider the system impulse response  $f(t)$ . Does  $f(t)$  have a Fourier transform? Justify your answer.

NO.  $F(\omega)$  does not converge because the  $j\omega$ -axis is not in the ROC of  $F(s)$ .

Problem 3, cont...

- (d) **11 pts.** A new system  $H$  is formed by adding negative feedback to  $F$  as shown in the figure below.  $H$  is both LTI and causal.

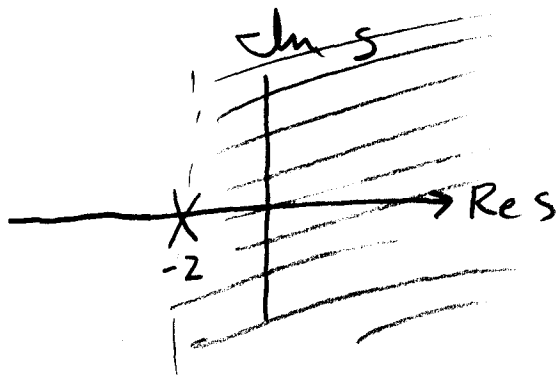


The transfer function of causal LTI system  $G$  is given by  $G(s) = 4$ . Find the transfer function  $H(s)$  of the overall system  $H$ .

$$\begin{aligned} H(s) &= \frac{F(s)}{1 + F(s)G(s)} = \frac{\frac{1}{s-2}}{1 + 4 \frac{1}{s-2}} \\ &= \frac{1/(s-2)}{1 + 4/(s-2)} = \frac{1}{s-2 + 4} \\ &= \underline{\underline{\frac{1}{s+2}}} \end{aligned}$$

Problem 3, cont...

- (e) 3 pts. Give a pole zero plot for  $H(s)$ . What is the ROC of  $H(s)$ ? Justify your answer.



Since  $H$  is causal, ROC is the right half-plane to the right of the rightmost pole.

$$\text{ROC: } \text{Re}[s] > -2$$

- (f) 2 pts. Is the system  $H$  BIBO stable? Justify your answer.

Yes.  $H$  is causal and all poles are in the LHP.

- (g) 2 pts. Consider the system impulse response  $h(t)$ . Does  $h(t)$  have a Fourier transform? Justify your answer.

Yes - because the  $j\omega$ -axis is in the ROC of  $H(s)$ .



4. 25 pts. The input  $x(t)$  and output  $y(t)$  of an LTI system  $H$  are related by

$$y''(t) + 5y'(t) + 6y(t) = 2x'(t) + 2x(t).$$

The initial conditions on the output are  $y(0^-) = 1$  and  $y'(0^-) = 2$ . Use the unilateral Laplace transform to find the system output for  $t > 0$  when the input is  $x(t) = e^{-t}u(t)$ .

$$\begin{aligned} s^2 Y(s) - sy(0^-) - y'(0^-) + 5[sY(s) - y(0^-)] + 6Y(s) \\ = 2[sX(s) - x(0^-)] + 2X(s) \end{aligned}$$

$$\rightarrow x(0^-) = 0:$$

$$s^2 Y(s) - s - 2 + 5sY(s) - 5 + 6Y(s) = 2sX(s) - 2 \cdot 0 + 2X(s)$$

$$[s^2 + 5s + 6] Y(s) - s - 7 = [2s + 2] X(s)$$

$$\rightarrow X(s) = \frac{1}{s+1}$$

$$[s^2 + 5s + 6] Y(s) - s - 7 = \frac{2s+2}{s+1} = \frac{2[s+1]}{s+1} = 2$$

$$[s^2 + 5s + 6] Y(s) = 9 + s$$

$$Y(s) = \frac{s+9}{s^2+5s+6} = \frac{s+9}{(s+2)(s+3)} = \frac{A}{s+2} + \frac{B}{s+3}$$

$$A = \left. \frac{s+9}{s+3} \right|_{s=-2} = \frac{7}{1} = 7; \quad B = \left. \frac{s+9}{s+2} \right|_{s=-3} = \frac{6}{-1} = -6$$

$$Y(s) = \frac{7}{s+2} - \frac{6}{s+3}$$

$$y(t) = 7e^{-2t}u(t) - 6e^{-3t}u(t)$$

More Work Space for Problem 4...