

# ECE 4213/5213

## Test 1

Wednesday, October 21, 2015

4:30 PM - 5:45 PM

Fall 2015

Name: SOLUTION

Dr. Havlicek

Student Num: \_\_\_\_\_

**Directions:** This test is open book. You may also use a calculator, a clean copy of the course notes, and a clean copy of the formula sheet from the course web site. Other materials are not allowed. You have 75 minutes to complete the test. All work must be your own.

**Students enrolled for undergraduate credit:** work any four problems. Each problem counts 25 points. Below, circle the numbers of the four problems you wish to have graded.

**Students enrolled for graduate credit:** work all five problems. Each problem counts 20 points.

SHOW ALL OF YOUR WORK for maximum partial credit!

### GOOD LUCK!

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SCORE:

1. (25/20) \_\_\_\_\_

2. (25/20) \_\_\_\_\_

3. (25/20) \_\_\_\_\_

4. (25/20) \_\_\_\_\_

5. (25/20) \_\_\_\_\_

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TOTAL (100):

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*On my honor, I affirm that I have neither given nor received inappropriate aid in the completion of this test.*

Signed: \_\_\_\_\_

Date: \_\_\_\_\_

1. 25/20 pts. A stable discrete-time LTI system  $H$  has input  $x[n]$  and output  $y[n]$  related by

$$y[n] - y[n-1] - \frac{3}{4}y[n-2] = x[n] - 2x[n-1].$$

- (a) 6/5 pts. Find the transfer function  $H(z)$ .

$$z: Y(z) - z^{-1}Y(z) - \frac{3}{4}z^{-2}Y(z) = X(z) - 2z^{-1}X(z)$$

$$Y(z) \left[ 1 - z^{-1} - \frac{3}{4}z^{-2} \right] = X(z) \left[ 1 - 2z^{-1} \right]$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 - 2z^{-1}}{1 - z^{-1} - \frac{3}{4}z^{-2}} = \frac{1 - 2z^{-1}}{(1 + \frac{1}{2}z^{-1})(1 - \frac{3}{2}z^{-1})} //$$

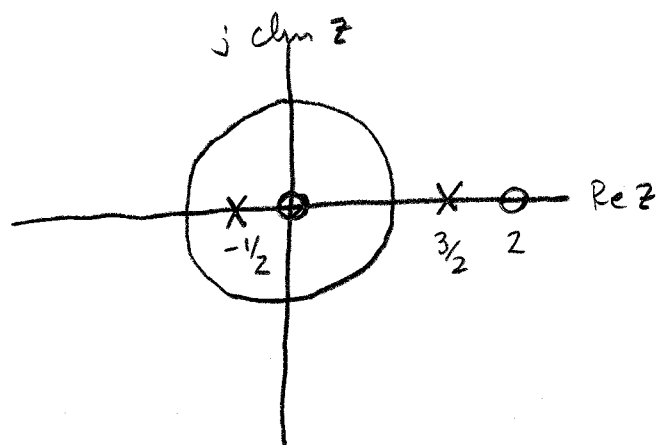
$$\text{Note: } \frac{z^2}{z^2} H(z) = \frac{z(z-2)}{(z+\frac{1}{2})(z-\frac{3}{2})} \quad (*)$$

- (b) 5/4 pts. Give a pole-zero plot for  $H(z)$  and specify the ROC.

From (\*) above:

poles:  $z = -1/2, z = 3/2$

zeros:  $z = 0, z = 2$



Because  $H$  is stable, the ROC must include the unit circle.

$$\text{ROC: } \frac{1}{2} < |z| < \frac{3}{2}$$

- (c) 2/2 pts. Is the system  $H$  causal? Justify your answer.

Because the ROC is an annulus, the impulse response must be two-sided  $\Rightarrow$  can't be causal.

Problem 1, cont...

(d) 12/9 pts. Find the impulse response  $h[n]$ .

$$H(z) = \frac{1 - 2z^{-1}}{(1 + \frac{1}{2}z^{-1})(1 - \frac{3}{2}z^{-1})} = \frac{A}{1 + \frac{1}{2}z^{-1}} + \frac{B}{1 - \frac{3}{2}z^{-1}}, \quad \frac{1}{2} < |z| < \frac{3}{2}$$

$$A = \left. \frac{1 - 2\theta}{1 - \frac{3}{2}\theta} \right|_{\theta = -2} = \frac{1 + 4}{1 + 3} = \frac{5}{4}$$

$$B = \left. \frac{1 - 2\theta}{1 + \frac{1}{2}\theta} \right|_{\theta = \frac{2}{3}} = \frac{1 - \frac{4}{3}}{1 + \frac{1}{3}} = \frac{-\frac{1}{3}}{\frac{4}{3}} = -\frac{3}{4} \cdot \frac{1}{3} = -\frac{1}{4}$$

$$H(z) = \underbrace{\frac{5/4}{1 + \frac{1}{2}z^{-1}}}_{|z| > \frac{1}{2}} - \underbrace{\frac{1/4}{1 - \frac{3}{2}z^{-1}}}_{|z| < \frac{3}{2}}$$

Table ↗

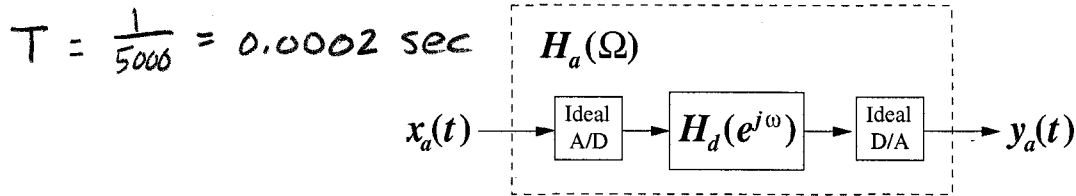
$$\frac{5}{4} \left(-\frac{1}{2}\right)^n u[n]$$

Table ↘

$$-\frac{1}{4} \left(\frac{3}{2}\right)^n u[-n-1]$$

$$h[n] = \frac{5}{4} \left(-\frac{1}{2}\right)^n u[n] + \frac{1}{4} \left(\frac{3}{2}\right)^n u[-n-1]$$

2. 25/20 pts. The continuous-time LTI system  $H_a(\Omega)$  shown in the figure below is implemented using an ideal A/D converter, a discrete-time LTI system  $H_d(e^{j\omega})$ , and an ideal D/A converter.



The sampling frequency of the A/D and D/A converters is  $F_T = 5 \text{ kHz}$ , so  $\Omega_T = 10,000\pi \text{ rad/sec}$ . All input signals  $x_a(t)$  are bandlimited to  $|\Omega| < \Omega_T/2$  (this simply ensures that the overall structure shown in the figure will be an LTI system).

The impulse response of the continuous-time filter  $H_a$  is given by

$W = 2000\pi$

$$h_a(t) = \delta(t) - \frac{\sin 2000\pi t}{\pi t}$$

$\delta(t) \leftrightarrow 1$

$\frac{\sin Wt}{\pi t} \xleftrightarrow{F} \text{rect}_{-W/2, W/2}$

- (a) 8/6 pts. Find the continuous-time frequency response  $H_a(\Omega)$ .

Table:  $H_a(\Omega) = 1 - \text{rect}_{-2000\pi, 2000\pi} = \text{rect}_{-10000\pi, 10000\pi}$

$$H_a(\Omega) = \begin{cases} 1, & |\Omega| > 2000\pi \\ 0, & |\Omega| < 2000\pi \end{cases}$$

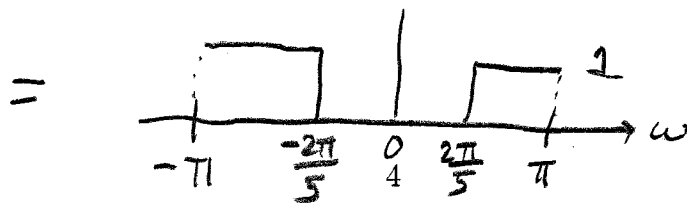
- (b) 8/7 pts. Find the discrete-time frequency response  $H_d(e^{j\omega})$ .

$$\omega = \Omega T = \frac{\Omega}{5000}$$

$$H_d(e^{j\omega}) = H_a\left(\frac{\omega}{T}\right), |\omega| < \pi$$

$$H_d(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi}{5} \leq |\omega| \leq \pi \\ 0, & |\omega| < \frac{2\pi}{5} \end{cases}$$

( $2\pi$ -periodic)



Problem 2, cont...

(c) 9/7 pts. Find the discrete-time impulse response  $h_d[n]$ .

$$H_d(e^{j\omega}) = \text{[Rectangular pulse from } -\pi \text{ to } \pi \text{ with height 1]} - \text{[Rectangular pulse from } -\frac{2\pi}{5} \text{ to } \frac{2\pi}{5} \text{ with height 1]}$$

Table  $\swarrow$   
 $\delta[n]$

$\searrow$  Table  
 $\frac{\sin \frac{2\pi}{5} n}{\pi n}$

$$h_d[n] = \delta[n] - \frac{\sin \frac{2\pi}{5} n}{\pi n}$$

3. 25/20 pts. A discrete-time LTI system  $H$  has impulse response

$$h[n] = 3^n u[n] + \left(-\frac{1}{3}\right)^n u[n].$$

The input is given by  $x[n] = \left(\frac{1}{2}\right)^n u[n]$ .

(a) 3/2 pts. Is the system  $H$  causal? *Justify your answer.*

The system is causal because  $h[n] = 0 \forall n < 0$ .

(b) 8/7 pts. Find the transfer function  $H(z)$  and give a pole-zero plot. Don't forget to specify the ROC.

Table:  $3^n u[n] \xleftrightarrow{Z} \frac{1}{1-3z^{-1}}, |z| > 3$   
 $\left(-\frac{1}{3}\right)^n u[n] \xleftrightarrow{Z} \frac{1}{1+\frac{1}{3}z^{-1}}, |z| > \frac{1}{3}$

$$H(z) = \frac{1}{1-3z^{-1}} + \frac{1}{1+\frac{1}{3}z^{-1}}$$

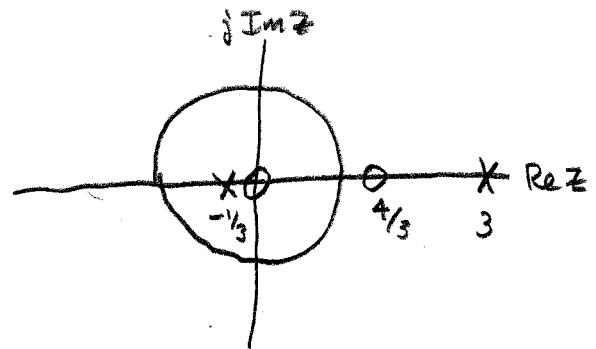
$$= \frac{1+\frac{1}{3}z^{-1} + 1-3z^{-1}}{(1-3z^{-1})(1+\frac{1}{3}z^{-1})}$$

$$= \frac{2 - \frac{8}{3}z^{-1}}{(1-3z^{-1})(1+\frac{1}{3}z^{-1})}$$

$$= \frac{2(1 - \frac{4}{3}z^{-1})}{(1-3z^{-1})(1+\frac{1}{3}z^{-1})} //$$

$$\left\{ = \frac{2z(z - \frac{4}{3})}{(z-3)(z+\frac{1}{3})} \right\}$$

poles:  $z=3, z=-\frac{1}{3}$   
 zeros:  $z=0, z=\frac{4}{3}$



Because  $H$  is causal, the ROC must be exterior to the largest pole.

$$\text{ROC: } |z| > 3 //$$

(c) 3/2 pts. Is the system  $H$  BIBO stable? *Justify your answer.*

The system is not stable because the ROC does not include the unit circle.

Alternate Answer: not stable because  $H$  is causal and the pole at  $z=3$  is outside the unit circle.

Problem 3, cont...

(d) 3/2 pts. Could the discrete-time Fourier transform (DTFT) be used to find the system output  $y[n]$ ? Briefly explain why or why not.

The DTFT could not be used because  $H(e^{j\omega})$  does not exist (the DTFT of  $h[n]$  diverges).

The reason is that  $H(e^{j\omega})$  is equal to  $H(z)$  evaluated on the unit circle, but in this case the unit circle is not in the ROC of  $H(z)$ .

(e) 8/7 pts. Use the  $z$ -transform to find the system output  $y[n]$ .

Table:  $X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}}, |z| > \frac{1}{2}$

$$Y(z) = X(z)H(z) = \frac{2(1 - \frac{4}{3}z^{-1})}{(1 - 3z^{-1})(1 + \frac{1}{3}z^{-1})(1 - \frac{1}{2}z^{-1})}, |z| > 3$$

$$= \frac{A}{1 - 3z^{-1}} + \frac{B}{1 + \frac{1}{3}z^{-1}} + \frac{C}{1 - \frac{1}{2}z^{-1}}$$

$$A = \frac{2(1 - \frac{4}{3}\theta)}{(1 + \frac{1}{3}\theta)(1 - \frac{1}{2}\theta)} \Big|_{\theta = \frac{1}{3}} = \frac{2(1 - \frac{4}{9})}{(1 + \frac{1}{9})(1 - \frac{1}{6})} = \frac{2(\frac{5}{9})}{\frac{10}{9} \cdot \frac{5}{6}} = \frac{10}{10 \cdot \frac{5}{6}} = \frac{6}{5}$$

$$B = \frac{2(1 - \frac{4}{3}\theta)}{(1 - 3\theta)(1 - \frac{1}{2}\theta)} \Big|_{\theta = -3} = \frac{2(1 + 4)}{(1 + 9)(1 + \frac{3}{2})} = \frac{2 \cdot 5}{10(\frac{5}{2})} = \frac{2}{5}$$

$$C = \frac{2(1 - \frac{4}{3}\theta)}{(1 - 3\theta)(1 + \frac{1}{3}\theta)} \Big|_{\theta = 2} = \frac{2(1 - \frac{8}{3})}{(1 - 6)(1 + \frac{2}{3})} = \frac{2(-\frac{5}{3})}{(-5)(\frac{5}{3})} = \frac{2}{5}$$

$$Y(z) = \underbrace{\frac{6/5}{1 - 3z^{-1}}}_{|z| > 3} + \underbrace{\frac{2/5}{1 + \frac{1}{3}z^{-1}}}_{|z| > \frac{1}{3}} + \underbrace{\frac{2/5}{1 - \frac{1}{2}z^{-1}}}_{|z| > \frac{1}{2}}, |z| > 3$$

Table ↗  
 $\frac{6}{5} 3^n u[n]$

Table ↓  
 $\frac{2}{5} (-\frac{1}{3})^n u[n]$

Table ↘  
 $\frac{2}{5} (\frac{1}{2})^n u[n]$

$$y[n] = \frac{6}{5} 3^n u[n] + \frac{2}{5} (-\frac{1}{3})^n u[n] + \frac{2}{5} (\frac{1}{2})^n u[n]$$

4. 25/20 pts. A discrete-time LTI system  $H$  has impulse response

$$h[n] = \left(\frac{1}{2}\right)^n \sin\left[\frac{\pi}{4}(n-1)\right] u[n-1].$$

(a) 11/9 pts. Find the transfer function  $H(z)$ . Don't forget to specify the ROC.

$$h[n] = \frac{1}{2} \left(\frac{1}{2}\right)^{n-1} \sin\left[\frac{\pi}{4}(n-1)\right] u[n-1]$$

$$\text{Let } g[n] = \left(\frac{1}{2}\right)^n \sin\left(\frac{\pi}{4}n\right) u[n] \mapsto h[n] = \frac{1}{2} g[n-1]$$

$$\rightarrow \text{Then } H(z) = \frac{1}{2} z^{-1} G(z)$$

Table  $(r = \frac{1}{2}, \omega_0 = \frac{\pi}{4})$  :  $G(z) = \frac{\left[\frac{1}{2} \sin \frac{\pi}{4}\right] z^{-1}}{1 - \left[2\left(\frac{1}{2}\right) \cos \frac{\pi}{4}\right] z^{-1} + \left(\frac{1}{2}\right)^2 z^{-2}}$

$$= \frac{\frac{1}{2} \frac{\sqrt{2}}{2} z^{-1}}{1 - \frac{\sqrt{2}}{2} z^{-1} + \frac{1}{4} z^{-2}} = \frac{\frac{1}{2\sqrt{2}} z^{-1}}{1 - \frac{1}{\sqrt{2}} z^{-1} + \frac{1}{4} z^{-2}}, |z| > \frac{1}{2}$$

$$H(z) = \frac{1}{2} z^{-1} G(z) = \frac{\frac{1}{4\sqrt{2}} z^{-2}}{1 - \frac{1}{\sqrt{2}} z^{-1} + \frac{1}{4} z^{-2}}, |z| > \frac{1}{2}$$


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Problem 4, cont...

(b) 3/2 pts. Find the frequency response  $H(e^{j\omega})$ .

$$H(e^{j\omega}) = H(z) \Big|_{z=e^{j\omega}} = \frac{\frac{1}{4\sqrt{2}} e^{-j2\omega}}{1 - \frac{1}{\sqrt{2}} e^{-j\omega} + \frac{1}{4} e^{-j2\omega}} //$$

(c) 11/9 pts. The system input is given by  $x[n] = \cos \frac{\pi}{2}n$ . Find the output  $y[n]$ .

The input is a sum of two eigenfunctions.

Notes p. 3-114:  $y[n] = |H(e^{j\pi/2})| \cos \left[ \frac{\pi}{2}n + \arg H(e^{j\pi/2}) \right]$

$$H(e^{j\pi/2}) = \frac{\frac{1}{4\sqrt{2}} e^{-j\pi}}{1 - \frac{1}{\sqrt{2}} e^{-j\pi/2} + \frac{1}{4} e^{-j\pi}} = \frac{-\frac{1}{4\sqrt{2}}}{1 + j\frac{1}{\sqrt{2}} - \frac{1}{4}}$$

$e^{-j\pi} = -1$   
 $e^{-j\pi/2} = -j$

$$= \frac{-\frac{1}{4\sqrt{2}}}{\frac{3}{4} + j\frac{1}{\sqrt{2}}}$$

$$|H(e^{j\pi/2})| = \left| \frac{-\frac{1}{4\sqrt{2}}}{\frac{3}{4} + j\frac{1}{\sqrt{2}}} \right| = \frac{\frac{1}{4\sqrt{2}}}{\left| \frac{3}{4} + j\frac{1}{\sqrt{2}} \right|} = \frac{\frac{1}{4\sqrt{2}}}{\sqrt{\left(\frac{3}{4}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2}} = \frac{\frac{1}{4\sqrt{2}}}{\sqrt{\frac{9}{16} + \frac{1}{2}}}$$

$$= \frac{\frac{1}{4\sqrt{2}}}{\sqrt{\frac{9}{16} + \frac{8}{16}}} = \frac{\frac{1}{4\sqrt{2}}}{\sqrt{\frac{17}{16}}} = \frac{\frac{1}{4\sqrt{2}}}{\frac{\sqrt{17}}{4}} = \frac{4}{\sqrt{17}} \cdot \frac{1}{4\sqrt{2}}$$

$$= \frac{1}{\sqrt{17}\sqrt{2}} = \frac{1}{\sqrt{34}} \approx 0.17150$$

$$\arg H(e^{j\pi/2}) = \arg \frac{1}{4\sqrt{2}} \frac{-1}{\frac{3}{4} + j\frac{1}{\sqrt{2}}} = \arg \frac{-1}{\frac{3}{4} + j\frac{1}{\sqrt{2}}} = \arg(-1) - \arg\left(\frac{3}{4} + j\frac{1}{\sqrt{2}}\right)$$

$$= \pi - \arctan \frac{1/\sqrt{2}}{3/4} = \pi - \arctan \frac{4}{3\sqrt{2}}$$

$$\approx \pi - 0.75597 = 2.38562$$

$$y[n] = 0.17150 \cos \left[ \frac{\pi}{2}n + 2.38562 \right]$$

5. 25/20 pts. Let  $x[n]$  and  $h[n]$  be 4-point discrete-time signals given by

$$\begin{aligned} x[n] &= [3 \ 1 \ 4 \ 1] \\ &= 3\delta[n] + \delta[n-1] + 4\delta[n-2] + \delta[n-3], \quad 0 \leq n \leq 3, \end{aligned}$$

and

$$\begin{aligned} h[n] &= [5 \ -9 \ 2 \ -6] \\ &= 5\delta[n] - 9\delta[n-1] + 2\delta[n-2] - 6\delta[n-3], \quad 0 \leq n \leq 3. \end{aligned}$$

(a) 13/10 pts. Use the DFT to find the 4-point circular convolution  $y_c[n] = x[n] \circledast h[n]$ .

$$\begin{aligned} X[k] &= \sum_{n=0}^3 x[n] W_4^{nk} = 3W_4^{0k} + W_4^k + 4W_4^{2k} + W_4^{3k} \\ &= 3 + W_4^k + 4W_4^{2k} + W_4^{3k}, \quad 0 \leq k \leq 3 \end{aligned}$$

$$H[k] = \sum_{n=0}^3 h[n] W_4^{nk} = 5 - 9W_4^k + 2W_4^{2k} - 6W_4^{3k}, \quad 0 \leq k \leq 3$$

$$\begin{aligned} Y_c[k] &= X[k]H[k] = (3 + W_4^k + 4W_4^{2k} + W_4^{3k})(5 - 9W_4^k + 2W_4^{2k} - 6W_4^{3k}) \\ &= 15 - 27W_4^k + 6W_4^{2k} - 18W_4^{3k} \\ &\quad + 5W_4^k - 9W_4^{2k} + 2W_4^{3k} - 6W_4^{4k} \\ &\quad + 20W_4^{2k} - 36W_4^{3k} + 8W_4^{4k} - 24W_4^{5k} \\ &\quad + 5W_4^{3k} - 9W_4^{4k} + 2W_4^{5k} - 6W_4^{6k} \end{aligned}$$

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$$Y_c[k] = 15 - 22W_4^k + 17W_4^{2k} - 47W_4^{3k} - 7W_4^{4k} - 22W_4^{5k} - 6W_4^{6k}$$

But  $W_4 = e^{-j\frac{2\pi}{4}}$ . So  $W_4^{4k} = e^{-j\frac{2\pi}{4}4k} = e^{-j2\pi k} = 1$

$$W_4^{5k} = W_4^{4k} W_4^k = W_4^k$$

$$W_4^{6k} = W_4^{4k} W_4^{2k} = W_4^{2k}$$

$$\begin{aligned} \Rightarrow Y_c[k] &= 15 - 22W_4^k + 17W_4^{2k} - 47W_4^{3k} - 7 - 22W_4^k - 6W_4^{2k} \\ &= 8 - 44W_4^k + 11W_4^{2k} - 47W_4^{3k}, \quad 0 \leq k \leq 3 \end{aligned}$$

Problem 5, cont... (more workspace for part 5(a))

From the last page:

$$\begin{aligned} Y_c[k] &= 8 - 44W_4^k + 11W_4^{2k} - 47W_4^{3k} \\ &= 8W_4^{0k} - 44W_4^k + 11W_4^{2k} - 47W_4^{3k}, \quad 0 \leq k \leq 3 \quad (*) \end{aligned}$$

By definition,

$$Y_c[k] = \sum_{n=0}^3 y_c[n] W_4^{nk} = y_c[0] W_4^{0k} + y_c[1] W_4^k + y_c[2] W_4^{2k} + y_c[3] W_4^{3k} \quad (**)$$

Comparing (\*) and (\*\*),

$$y_c[0] = 8 \quad y_c[1] = -44 \quad y_c[2] = 11 \quad y_c[3] = -47$$

$$\begin{aligned} y_c[n] &= [8 \quad -44 \quad 11 \quad -47] \\ &= 8\delta[n] - 44\delta[n-1] + 11\delta[n-2] - 47\delta[n-3], \quad 0 \leq n \leq 3 \end{aligned}$$

Problem 5, cont...

(b) 12/10 pts. Now use the DFT to find the linear convolution  $y_e[n] = x[n] \circledast h[n]$ .

$N_1 = N_2 = 4 \Rightarrow N = N_1 + N_2 - 1 = 7 \Rightarrow$  zero pad both sequences to length  $N = 7$ .

$$x_7[n] = [3 \ 1 \ 4 \ 1 \ 0 \ 0 \ 0]$$

$$X_7[k] = \sum_{n=0}^6 x_7[n] W_7^{nk}$$

$$= 3 + W_7^k + 4W_7^{2k} + W_7^{3k}, \quad 0 \leq k \leq 6$$

$$h_7[n] = [5 \ -9 \ 2 \ -6 \ 0 \ 0 \ 0]$$

$$H_7[k] = \sum_{n=0}^6 h_7[n] W_7^{nk}$$

$$= 5 - 9W_7^k + 2W_7^{2k} - 6W_7^{3k}, \quad 0 \leq k \leq 6$$

$$Y_e[k] = X_7[k] H_7[k] = (3 + W_7^k + 4W_7^{2k} + W_7^{3k})(5 - 9W_7^k + 2W_7^{2k} - 6W_7^{3k})$$

$$= 15 - 27W_7^k + 6W_7^{2k} - 18W_7^{3k}$$

$$+ 5W_7^k - 9W_7^{2k} + 2W_7^{3k} - 6W_7^{4k}$$

$$+ 20W_7^{2k} - 36W_7^{3k} + 8W_7^{4k} - 24W_7^{5k}$$

$$+ 5W_7^{3k} - 9W_7^{4k} + 2W_7^{5k} - 6W_7^{6k}$$

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$$Y_e[k] = 15 - 22W_7^k + 17W_7^{2k} - 47W_7^{3k} - 7W_7^{4k} - 22W_7^{5k} - 6W_7^{6k}, \quad 0 \leq k \leq 6$$

(This could have been deduced from the work in part (a))

By definition,  $Y_e[k] = \sum_{n=0}^6 y_e[n] W_7^{nk}$

$$= y_e[0] + y_e[1]W_7^k + y_e[2]W_7^{2k} + y_e[3]W_7^{3k} + y_e[4]W_7^{4k}$$

$$+ y_e[5]W_7^{5k} + y_e[6]W_7^{6k}, \quad 0 \leq k \leq 6$$

Comparing this to the result above and "picking off" the  $y_e[n]$  values,

$$y_e[n] = [15 \ -22 \ 17 \ -47 \ -7 \ -22 \ -6]$$

$$= 15\delta[n] - 22\delta[n-1] + 17\delta[n-2] - 47\delta[n-3] - 7\delta[n-4]$$

$$- 22\delta[n-5] - 6\delta[n-6],$$

$$0 \leq n \leq 6$$